Empirical modelling of production decisions of heterogeneous farmers with mixed models

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Accounting for unobserved heterogeneity in micro-econometric agricultural production models: a random parameter approach

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Abstract. To account for the effects of heterogeneity in micro-econometric models has been major concern in labor economics, empirical industrial organization or trade economics for at least two decades. The micro-econometric agricultural production choice models found in the literature largely ignore the impacts of unobserved heterogeneity. This can partly be explained by the dimension of these models which deal with large choice sets, *e.g.*, acreage choices, input demands and yield supplies.

We propose a random parameter framework to account for the unobserved heterogeneity in micro-econometric agricultural production choices models. This approach allows accounting for unobserved farms' and farmers' heterogeneity in a fairly flexible way. We estimate a system of yield supply and acreage choice equations with a panel set of French crop growers. Our results show that heterogeneity significantly matters in our empirical application and that ignoring the heterogeneity of farmers' choice processes can have important impacts on simulation outcomes.

Due to the dimension of the estimation problem and the functional form of the considered production choice model, the Simulated Maximum Likelihood approach usually considered in the applied econometrics literature in such context is empirically intractable. We show that specific versions of the Stochastic Expectation-Maximization algorithms proposed in the statistics literature can be implemented.

Keywords. Unobserved heterogeneity, random parameter models, agricultural production choices

JEL codes: Q12, C13, C15

Accounting for unobserved heterogeneity in micro-econometric agricultural production models: a random parameter approach

Evidences of the effects of unobserved heterogeneity in micro-econometric models are now pervasive in many applied economics fields. During the last two decades applied micro-econometricians have developed tools to estimate models explicitly accounting for the effects of unobserved heterogeneity on economic choices. These tools have already been successfully used in several applied economics domains. Empirical studies highlighting the role of unobserved heterogeneity effects in econometric models can be found, *e.g.*, in labor economics (see, *e.g.*, Heckman, 2001), in empirical industrial organization (see, *e.g.*, Ackerberg *et al* 2007) or in international trade economics (see, *e.g.*, Eaton *et al* 2011). An important point is that the effects of unobserved heterogeneity are not simply "extracted" from the error terms of the considered models. These effects also affect the responses of these models to important interest variables.

Our view is that similar heterogeneity features characterize agricultural production choices. Farms and farmers are heterogeneous and this heterogeneity affects the way farmers respond to, *e.g.*, economic incentives. However, the micro-econometric agricultural production choice models found in the literature largely ignore the impacts of unobserved heterogeneity. This can partly be explained by the dimension of these models which deal with large choice sets, *e.g.* acreage choices, input demands and yield supplies in the so-called multicrop models.

The objectives of this article are twofold. First, we aim at showing that tools recently developed by micro-econometricians and statisticians allow specification and estimation of econometric agricultural production choice models accounting for farms' and farmers' unobserved heterogeneity in a fairly flexible way. Second, we aim at showing that unobserved heterogeneity effects significantly matter in empirical agricultural production choice models.

Farmers face different production conditions due to heterogeneous soil quality or usual climatic conditions across space. They also own different machineries and different wealth levels. Finally, farmers are also different because of their various educational level or abilities, as well as because they may have different objectives with respect to income risk or with respect to the leisure *versus* labor trade-off. These heterogeneity sources are likely to have important impacts on farmers' production choices. To control for the effects of these heterogeneity sources is difficult in practice. As suggested by the short list given above, potential heterogeneity sources are numerous. Furthermore many heterogeneity sources are not suitably described in the data sets usually used by agricultural economists. As a result, empirical investigators generally rely on a few variables – *e.g.* farms' size, farmers' age, farmers' education, farms' location or, when available, rough soil quality indices – to control for the effects of many heterogeneity sources on farmers' production choices. As a matter of fact, numerous important heterogeneity sources are unobserved for agricultural production modeling.

Means usually employed by agricultural production economists to cope with the unobserved heterogeneity of farms and farmers depend on their modeling approaches and purposes. Mathematical programming models used to analyze agricultural supply responses to economic policies (or other determinants of farmers' choices) are usually built by considering sets of farms, of small regions or of farm-types. A mathematical programming model is calibrated for each element of the considered set of "farms". This disaggregated calibration procedure allows controlling for farms' and farmers' unobserved heterogeneity. Of course the lack of statistical background of the standard calibration procedures is often pointed out as a major limitation of agricultural supply mathematical programming models (Howitt 1995 ; Heckeleï and Wolff 2003 ; Heckeleï *et al* 2012). However, the simulations provided by these models appear to be highly valued by decision-makers. These provide disaggregated results

with respect to the simulated effects of agricultural policy measures on farmers' choices across more or less large geographical areas. By comparison, the ability of micro-econometric models of agricultural production choices to account for farms' and farmers' heterogeneity is much more limited. As recalled above, only a few control variables are usually available to agricultural production economists. Standard specifications of econometric agricultural production choice models can be defined as a sum of a deterministic part and of a vector of random error terms. In these models, farmers' responses to economic (or other) incentives are governed by the deterministic part – *i.e.* by a few statistically estimated parameters – and the effects of farms' and farmers' unobserved heterogeneity are "pushed" into additively separable error terms. This often leads to simulation results which are unrealistically homogeneous across farms.

The agricultural production choice models proposed in this article allow accounting for farms' and farmers' unobserved heterogeneity while being empirically tractable. We adopt the random parameter modeling framework because it allows estimating standard production choice models under the assumption that the model parameters are farmer specific. Standard data set, even panel data sets, do not permit direct estimation of the individual parameters. The objective of the estimation is to characterize the distribution of the model parameters across the considered farmer population. These random parameter models can be used to design simulation models in which a parameter vector is "statistically calibrated" for each sampled farmer, providing reliable alternatives to the calibrated mathematical programming models usually used for investigating the effects of agricultural policy instruments.

We illustrate these points through the specification and the estimation of a multicrop econometric model with random parameters. The Multinomial Logit (MNL) framework proposed by Carpentier and Letort (2014) is chosen due to its simplicity, to its parameter

parsimony and to the easy interpretation of its parameters. The specified model being parametric, we rely on the Maximum Likelihood (ML) framework for its estimation. More specifically we use estimators and optimization procedures specifically designed by statisticians for the estimation of a class of models to which random parameter models belong.

Econometricians mostly use Simulated Maximum Likelihood (SML) estimators for estimating random parameter models when the probability distribution of the random parameters is continuous (Jank and Booth, 2003). SML estimators allow solving the integration problem of the sample likelihood function of such models with simulation methods. But they are intractable for our application due to the complexity of the sample simulated likelihood function.

A Simulated Expectation-Maximization (SEM) algorithm allows overcoming this problem. The Expectation-Maximization (EM) algorithm proposed by Dempster *et al* (1997) is particularly well-suited for maximizing likelihood functions involving missing variables such as random parameters. It consists in iterating an expectation step (E step) and a Maximization step (M step) until numerical convergence. The SEM algorithms proposed in the statistics literature allow computing estimators having the asymptotic properties of SML estimators. Because they split a large and complex maximization problem into a sequence of simple – very simple in our case – maximization problems, they are empirically tractable in cases where SML estimators are very difficult to obtain.

The algorithm we propose is a Stochastic Approximation EM (SAEM) algorithm (Delyon *et al*, 1999) using a Conditional M (CM) step (Meng and Rubin, 1993) and the importance sampling simulator used, *e.g.*, by Caffo *et al* (2005) or Train (2007, 2008). It is fairly easy to code and only involves simple operations.

The empirical application considers a sample of French crop producers observed from 2004 to 2007. Obtained results demonstrate that unobserved heterogeneity matters for the modeling of micro-economic agricultural production choices, even within a small area. Key parameters of farmers' choice models are significantly affected by unobserved heterogeneity effects, *i.e.* exhibit significant variability across farmers. We also show how random parameter models can be used to "statistically calibrate" a multicrop simulation model based on a sample of heterogeneous farms. Simulation results show that it is important for the estimated models to allow farmers to respond heterogeneously to homogeneous economic incentives.

The general features of random parameter models are presented in the first section, together with their main advantages and limitations. The second section presents the multicrop econometric model that we consider in order to investigate the advantages of accounting for unobserved heterogeneity in agricultural production choice models. Identification and estimation issues are discussed in the third section. The estimation results and their interpretations are provided in the fourth section.

1. Unobserved heterogeneity and random parameter models

This section presents the main features of random parameter models of agricultural production choices. It also introduces important elements to be used in the presentation of the estimation issues. We consider short run production choices of farmers –*i.e.* an acreage (share) demand system and a yield supply system in the empirical application – and we take for granted that farmers' choices rely on heterogeneous determinants. We consider the use of panel data so that observations are indexed by $i = 1,...,N$ (farm/farmers) and $t = 1,...,T$ (year).

A random parameter model is composed of two parts. The first part of the model, the "behavioral model",[1] formally describes the causal process of interest and defines its statistical characteristics conditional on the considered random parameters (and on the exogenous variables). In our case the "behavioral model" is a standard agricultural production choice model in which some or all parameters are chosen to be farmer specific. Of course, this requires a careful examination of the statistical relationships between the random parameters and the other elements of the model, *i.e.* its explanatory variables and error terms. The second part of the model defines the distribution characteristics of the random parameters (conditional on the exogenous variables), *i.e.* the "mixing" distribution of the model according to the terminology used in statistics.

1.1. Behavioral model and "kernel" likelihood function

The equation

(1) $\mathbf{c}_{it} = \mathbf{r}(\mathbf{z}_{it}, \mathbf{e}_{it}; \mathbf{q}_i)$

describes the production choices $\mathbf{c}_{it}$ of farmer *i* in year *t* as a known response function **r** to the determinants of these choices $(\mathbf{z}_{it}, \mathbf{e}_{it})$, whether these determinants are observed or not. The term $\mathbf{z}_{it}$, respectively $\mathbf{e}_{it}$, is observed, respectively unobserved. The response function **r** is parameterized by a farmer specific parameter vector $\mathbf{q}_i$.[2] Note that if the random terms

[1] Or the "kernel model" according to Train's (2007, 2008) terminology.

[2] The use of latent variables provides an alternative to random parameter models. In this case the behavioral model can be defined as $\mathbf{c}_{it} = \mathbf{r}(\mathbf{z}_{it}, \mathbf{e}_{it}, \boldsymbol{\tau}_i; \boldsymbol{\theta})$ where $\boldsymbol{\theta}$ is a parameter vector to be estimated and $\boldsymbol{\tau}_i$ is a vector of latent variables aimed at characterizing heterogeneity such as productivity indices. These models add latent variables aiming at capturing unobserved heterogeneity effects in standard models. "Pure" random parameter models are defined as standard models with individual specific parameters. Random parameter models capture unobserved heterogeneity in a flexible way but involve more unobserved variables. Latent variable models

$(\mathbf{e}_{it}, \mathbf{q}_i)$ are unobserved to the econometrician, they are known to farmer *i* in *t* and partly determine its choices through their effects in **r**. Equation (1) is a deep structural model, or an "all causes" model. It defines how the choice of farmer *i*, $\mathbf{c}_{it}$, is caused by its determinants $(\mathbf{z}_{it}, \mathbf{e}_{it})$ up to the characteristics of this farmer and of his farm, $\mathbf{q}_i$. Equation (1) can be any agricultural production choice model where the usual fixed parameters, at least some of them, are replaced by farmer specific parameter vector $\mathbf{q}_i$.[3]

In a short run production choice context, the random parameter vector $\mathbf{q}_i$ mainly captures the effects of the farms' natural or quasi-fixed factor endowments, of the farmers' production technologies and of farmers' characteristics. The more these effects vary across farms in the considered population, the more likely is the distribution of $\mathbf{q}_i$ to exhibit significant variability. Our application considers short-run crop production choices and relies on a short panel data set, *i.e.* with $T = 4$. Farms and farmers' production technology generally evolves slowly over time. This allows assuming that the parameters $\mathbf{q}_i$ of the production choice model remain constant over a few years.

Equation (1) is completed by statistical assumptions in order to define the "behavioral model". It is assumed here that $\mathbf{z}_{it}$ and $\mathbf{e}_{it}$ are independent conditionally on $\mathbf{q}_i$. *I.e.* it is assumed that controlling for the farms' and farmers' characteristics ensures that $\mathbf{z}_{it}$ can be

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require assumptions related to the sources of unobserved heterogeneity and on how this heterogeneity affects the considered choices.

[3] The functional form of **r** can also be defined up to a fixed parameter vector to be estimated, as in our empirical application. The response function can also depend on available variables describing the farmers or/and or their farms (these may also be included in the vector $\mathbf{z}_{it}$). These extensions are technically straightforward and are ignored here to reduce the notational burden.

interpreted as purely exogenous factors – such as market prices or climatic events – affecting farmers' choices. It is further assumed that $\mathbf{q}_i$ and $\mathbf{e}_{it}$ are statistically independent. This assumption relies on the idea that $\mathbf{q}_i$ captures the permanent unobserved characteristics of farmer *i* affecting $\mathbf{x}_{it}$ while $\mathbf{e}_{it}$ mostly represents the effects of idiosyncratic shocks on $\mathbf{c}_{it}$ – *i.e.* $\mathbf{e}_{it}$ basically is a "standard" error term.

We assume that the probability distribution of $\mathbf{e}_{it}$ is characterized by the parametric probability density function $g(\mathbf{e}_{it};\boldsymbol{\mu}_t)$, implying that the considered "behavioral model" is parametric. The term $\boldsymbol{\mu}_t$ is a parameter vector to be estimated. The probability density function of $\mathbf{e}_{it}$ and equation (1) allows computing the probability density function of $\mathbf{c}_{it}$ conditional on $(\mathbf{z}_{it},\mathbf{q}_i)$ parameterized by $\boldsymbol{\mu}_t$, $f(\mathbf{c}_{it} \mid \mathbf{z}_{it},\mathbf{q}_i;\boldsymbol{\mu}_t)$.[4]

Equation (1) and the independence assumptions described above define a "behavioral model" which can be used with cross-section data. With panel data additional assumptions are required in order to describe the potential dynamic features of the considered choices. It is assumed here that the modeled choice process is essentially static in the sense that $\mathbf{z}_{it}$ and $\mathbf{e}_{is}$ are independent conditionally on $\mathbf{q}_i$ for any pair of years (s,t).[5] This condition simplifies the exposition and is assumed to hold in our empirical application.

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[4] Assuming that the response function $\mathbf{r}$ is invertible in $\mathbf{e}_{it}$, *i.e.* that $\mathbf{e}_{it} = \mathbf{r}^{(-1)}(\mathbf{z}_{it},\mathbf{c}_{it};\mathbf{q}_i)$, this probability density function is given by

$$f(\mathbf{c}_{it} \mid \mathbf{z}_{it},\mathbf{q}_i;\boldsymbol{\mu}_t) = \left|\det\left(\tfrac{\partial}{\partial \mathbf{e}}\mathbf{r}(\mathbf{z}_{it},\mathbf{e}_{it};\mathbf{q}_i)\right)\right|^{-1} g(\mathbf{e}_{it};\boldsymbol{\mu}_t) \quad \text{where} \quad \mathbf{e}_{it} = \mathbf{r}^{(-1)}(\mathbf{z}_{it},\mathbf{c}_{it};\mathbf{q}_i),$$

the function $\mathbf{r}^{(-1)}$ denoting the inverse function in $\mathbf{e}_{it}$ of the response function $\mathbf{r}$.

[5] *I.e.* $\mathbf{z}_{it}$ is assumed to be weakly exogenous with respect to $\mathbf{e}_{it}$ according to the panel data econometrics terminology.

The production choices considered in our empirical application are modeled as static choices because the main dynamic aspects of crop production choices are due to crop rotations. Such dynamic effects can be suitably approximated by farmer specific parameters because crop rotation effects imply highly persistent dynamic effects in the crop production choices when farmers base their production choices on a few rotation schemes. Short run production choices are repeated each year and follow the same scheme as long as the production technology and the quasi-fixed factor endowment do not change.

These elements also provide arguments for assuming that the $\mathbf{e}_{it}$ terms are independent across *t*. Under these assumptions the joint density of the vector $\mathbf{c}_i \equiv (\mathbf{c}_{i1},...,\mathbf{c}_{iT})$ conditional on $(\mathbf{q}_i, \mathbf{z}_i)$, where $\mathbf{z}_i \equiv (\mathbf{z}_{i1},...,\mathbf{z}_{iT})$, is given by:

$$(2) \qquad f(\mathbf{c}_i \mid \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\mu}) = \prod_{t=1}^{T} f(\mathbf{c}_{it} \mid \mathbf{z}_{it}, \mathbf{q}_i; \boldsymbol{\mu}_t).$$

where $\boldsymbol{\mu} \equiv (\boldsymbol{\mu}_1,...,\boldsymbol{\mu}_T)$. Of course, farmers' choices are linked across time due to their relying on the same parameter vector $\mathbf{q}_i$. But these choices are assumed to be independent across time conditionally on $\mathbf{q}_i$.

1.2. Mixing probability distribution

The second part of a parametric random parameter model describes the distribution of the farmers' specific parameters $\mathbf{q}_i$ conditional on the explanatory variables $\mathbf{z}_{it}$. It is assumed here that $\mathbf{z}_i$ and $\mathbf{q}_i$ are independent because $\mathbf{z}_{it}$ contains exogenous determinants of the production choice $\mathbf{c}_{it}$, *i.e.* prices and year specific effects.[6] It implies that one just needs a statistical model for the probability distribution of $\mathbf{q}_i$. As in the empirical application, we

[6] In the empirical application presented in the next sections, $\mathbf{z}_{it}$ contains price variables which mostly vary across years and year dummies, ensuring that $\mathbf{q}_i$ and $\mathbf{z}_{it}$ can be considered as independent variables.

define a parametric model by using the probability density function $h(\boldsymbol{\theta}_i;\boldsymbol{\eta})$ which is defined up to the parameter vector $\boldsymbol{\eta}$ to be estimated. The probability distribution of $\boldsymbol{\theta}_i$ describes the distribution of $\boldsymbol{\theta}_i$ across the considered famers' population. The more the $\boldsymbol{\theta}_i$ varies across farmers, the more heterogeneity matters to model farmers' choices $\mathbf{c}_{it}$.

Specification of the role of $\boldsymbol{\theta}_i$ in the model of $\mathbf{c}_{it}$ depends on how unobserved heterogeneity effects are expected to affect farmers' choices. Standard panel data models generally assume that the effects of $\boldsymbol{\theta}_i$ and of $\mathbf{e}_{it}$ are additively separable in $\mathbf{r}$, with *e.g.* $\mathbf{r}(\mathbf{z}_{it},\mathbf{e}_{it};\boldsymbol{\theta}_i)=\boldsymbol{\rho}(\mathbf{z}_{it})+\boldsymbol{\theta}_i+\mathbf{e}_{it}$. In this case the so-called "individual effect" $\boldsymbol{\theta}_i$ does not affect the effect of $\mathbf{z}_{it}$ on $\mathbf{c}_{it}$, implying homogeneous responses of $\mathbf{c}_{it}$ to changes in $\mathbf{z}_{it}$. Keane (2009) discusses this point and highlights a basic trade-off. Econometric models defined as the sum of a deterministic part $\boldsymbol{\rho}(\mathbf{z}_{it})$ and of random terms $\boldsymbol{\theta}_i+\mathbf{e}_{it}$ are relatively easily estimated by using semi-parametric estimators. But such models do not suitably account for the effects of unobserved heterogeneity when these effects are not additively separable in the considered response functions, *i.e.* when $\frac{\partial}{\partial \mathbf{z}}\mathbf{r}(\mathbf{z}_{it},\mathbf{e}_{it};\boldsymbol{\theta}_i)$ actually depends on $\boldsymbol{\theta}_i$. By adopting a random parameter framework we allow interactions between $\mathbf{z}_{it}$ and $\boldsymbol{\theta}_i$ in $\mathbf{r}(\mathbf{z}_{it},\mathbf{e}_{it};\boldsymbol{\theta}_i)$.

Keane (2009) also argues that the use of relatively involved inference tools as well as parametric assumptions on the distribution of the random terms $(\mathbf{e}_{it},\boldsymbol{\theta}_i)$ may be a reasonable price for buying the opportunity to introduce rich unobserved heterogeneity effects in micro-econometric models. Of course, this trade-off is an empirical issue and depends on the modeled choice process. But empirical evidences accumulated in other applied economics fields suggest that it is worth investigating this trade-off for agricultural production choice

modeling. This is the main object of this article with a particular focus on the unobserved heterogeneity effects on farmers' responses to economic incentives.

Of course the choice of the "mixing" probability distribution, *i.e.* the parametric family of the probability distribution of $\mathbf{q}_i$, is crucial to suitably capture the unobserved heterogeneity effects in the considered model. Being related to unobserved variables, this choice basically is an empirical issue. It can be based on trials with different parametric models. Using flexible parametric models, *e.g.* finite discrete mixtures of Gaussian models, or non parametric models appears to be difficult in practice. Such models can only be used when the dimension of $\mathbf{q}_i$ is very small and with very large samples.

1.3. Likelihood function and statistical calibration of individual parameters

The probability distribution of the dependent variable $\mathbf{c}_i$ conditional on its observed determinants $\mathbf{z}_i$ is a key concept for estimation purposes. Its density function defines the likelihood function to be used in the ML framework. The density of $\mathbf{c}_i$ conditional on $\mathbf{z}_i$ is the mean of that of $\mathbf{c}_i$ conditional on $(\mathbf{z}_i, \mathbf{q}_i)$ integrated over the distribution of $\mathbf{q}_i$:

$$(3) \qquad f(\mathbf{c}_i \mid \mathbf{z}_i; \boldsymbol{\theta}) = \int f(\mathbf{c}_i \mid \mathbf{z}_i, \mathbf{q}; \boldsymbol{\mu}) h(\mathbf{q}; \boldsymbol{\eta}) d\mathbf{q} \,.$$

The term $\boldsymbol{\theta} \equiv (\boldsymbol{\mu}_1, ..., \boldsymbol{\mu}_T, \boldsymbol{\eta})$ is the "complete" parameter vector of the considered parametric random parameter model. The integral in equation (4) cannot be solved analytically in general but this issue is ignored for the moment.

Statistical estimates of $\boldsymbol{\theta}$ allow the investigation of the distribution of the random parameter $\mathbf{q}_i$. First, these estimates can be used to test the empirical relevance of the random parameter specification by checking whether $\mathbf{q}_i$ actually exhibits variations or not. If $\boldsymbol{\theta}$ contains "variance parameters" then simple parametric tests can be used. Second, the

estimates of $\boldsymbol{\theta}$ can also be used to interpret the empirical content of the $\mathbf{q}_i$ terms. *E.g.*, the statistical relations among the elements of $\mathbf{q}_i$ may suggest interpretations of their variations.

The statistical estimates of $\boldsymbol{\theta}$ can also be used to "statistically calibrate" a simulation model based on the considered random parameter model. This simulation model can be based on estimates of the parameters for each sampled farmer. The probability distribution of $\mathbf{q}_i$ is an *ex ante* or *prior* distribution of the random parameter. It describes the distribution of $\mathbf{q}_i$ in the considered farmer population. The minimum mean squared error estimator of $\mathbf{q}_i$ for any farmer taken at random in the considered population is simply the mean of $\mathbf{q}_i$, $E[\mathbf{q}_i]$. Of course, conditioning on the information set available for farmer *i* provides more accurate estimates, *i.e.* to condition on the information provided by $(\mathbf{c}_i, \mathbf{z}_i)$ allows defining more precise estimates of $\mathbf{q}_i$.[7] By application of Bayes' rule the probability density function of $\mathbf{q}_i$ conditional on $(\mathbf{c}_i, \mathbf{z}_i)$ is given by:

$$(4) \qquad h(\mathbf{q}_i \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}) = \omega(\mathbf{c}_i, \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\theta}) h(\mathbf{q}_i; \boldsymbol{\eta}) \quad \text{where} \quad \omega(\mathbf{c}_i, \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\theta}) \equiv \frac{f(\mathbf{c}_i \mid \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\mu})}{f(\mathbf{c}_i \mid \mathbf{z}_i; \boldsymbol{\theta})}.$$

The probability density function $h(\mathbf{q}_i \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta})$ – which is designated as the *ex post* or *a posteriori* density of $\mathbf{q}_i$ conditional on what is known about farmer *i* – can be used to integrate $E[\mathbf{q}_i \mid \mathbf{c}_i, \mathbf{z}_i]$, the best predictor of $\mathbf{q}_i$ conditional on $(\mathbf{c}_i, \mathbf{z}_i)$ according to the minimum squared prediction error criterion.[8] Note that the "weight term" $\omega(\mathbf{c}_i, \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\theta})$

[7] Even a single observation $(\mathbf{c}_{it}, \mathbf{z}_{it})$ for farmer *i* is valuable.

[8] We use the term "statistical calibration" instead of "estimation" or of "calibration" to refer to the computation of the individual parameter estimates for two reasons. An estimate of $E[\mathbf{q}_i \mid \mathbf{c}_i, \mathbf{z}_i]$ is not an estimate of $\mathbf{q}_i$ because its individual features only relies on the limited information available on farmer *i* provided by $(\mathbf{c}_i, \mathbf{z}_i)$. But, contrary to the calibrated value of $\mathbf{q}_i$ considered in mathematical programming models, the estimates of

directly links the *ex ante* and *ex post* probability density functions of the random parameter vector $\mathbf{q}_i$. This term plays a crucial "technical" role in what follows because it allows defining $h(\mathbf{q}_i \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta})$ from $h(\mathbf{q}_i; \boldsymbol{\eta})$.

2. A random parameter multicrop model

The multicrop model considered here is a random parameter version of a model proposed by Carpentier and Letort (2014). This model combines a Nested MNL acreage share model with quadratic yield functions. This section presents the main features of the model to be used in the empirical application.

The considered multicrop model assumes that farmers maximize their expected profit in two steps. First they maximize the expected return to each crop under the assumption that this return doesn't depend on the crop acreages. Second, farmers allocate land to different crops to maximize their expected profit provided that they incur implicit acreage management costs. These management costs provide incentive for crop diversification.

The crop set $\mathcal{K} \equiv \{0,1,...,K\}$ is partitioned into mutually exclusive crop groups $\mathcal{K}_g$ for $g \in \mathcal{G} \equiv \{0,1,...,G\}$.[9] The cardinality of $\mathcal{K}_g$ is denote by K_g. This partition is defined to account for the fact that different crops require different management efforts and compete more or less for, *e.g.*, quasi-fixed input uses. The groups are defined so that any crop compete more in the land allocation process with the other crops of its group than it does compete with

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$E[\mathbf{q}_i \mid \mathbf{c}_i, \mathbf{z}_i]$ are statistical in the sense that they depend on an estimate of $\boldsymbol{\theta}$ as well as on the considered random parameter model. This model basically is a statistical model structured by a few micro-economic assumptions.

[9] This partition allows defining a two-level Nested MNL acreage choice model. Further partitioning the crop groups allows defining multi-level Nested MNL acreage choice model.

crops of other groups. Group 0 contains a single crop, crop 0. As shown below, crop 0 plays a specific technical role in the model.

2.1. Multicrop behavioral model

The "behavioral" model of the considered multicrop model is an equation system composed of a yield supply sub-system

(5a) $y_{k,it} = \beta_{k,i} + \delta_{k,t} - 1/2 \times \gamma_k (w_{it} p_{k,it}^{-1})^2 + v_{k,it}$ for $k \in \mathcal{K}_g$ and $g = 0,1,...G$

and of an acreage share sub-system

(5b) $s_{k,it} = \dfrac{\exp(\rho_{g,i}\pi_{k,it})}{\sum_{\ell \in \mathcal{K}_g} \exp(\rho_{g,i}\pi_{\ell,it})} \dfrac{\left(\sum_{\ell \in \mathcal{K}_g} \exp(\rho_{g,i}\pi_{\ell,it})\right)^{\alpha_i \rho_{g,i}^{-1}}}{\sum_{h \in \mathcal{G}} \left(\sum_{\ell \in \mathcal{K}_h} \exp(\rho_{h,i}\pi_{\ell,it})\right)^{\alpha_i \rho_{h,i}^{-1}}}$ for $k \in \mathcal{K}_g$ and $g = 1,...,G$

where:

(5c) $\pi_{\ell,it} = p_{\ell,it}\beta_{\ell,i} + 1/2 \times \gamma_\ell w_{it}^2 p_{\ell,it}^{-1} - \zeta_{\ell,i} + u_{\ell,it}$ for $\ell \in \mathcal{K}_g$ and $g = 0,1,...,G$.

The yield supply function of crop *k* is obtained by maximizing in the aggregate variable input level the expected margin of crop *k* under the assumptions that the considered yield function is quadratic in the aggregate variable input level. Appendix A presents how the yield supply functions given in equation (5a) and the expected gross margin functions given in equation (5c) are derived and linked.

Equation (5a) defines the yield supply function of crop *k* as a function of the (anticipated) price of crop *k*, $p_{k,it}$, of the price of an aggregate variable input, w_{it}, and of a centered error term, $v_{k,it}$. This yield supply function also depends on crop specific year effect, $\delta_{k,t}$, and on a farmer specific random parameter $\beta_{k,i}$. The mean of $\beta_{k,i}$ being left unrestricted, the year specific fixed parameters $\delta_{k,t}$ are normalized by the constraint $\sum_{t=1}^{T} \delta_{k,t} = 0$. Provided that the

fixed curvature parameter γ_k needs to be positive for the yield function to be strictly concave, the farmer specific parameter $\beta_{k,i}$ can be interpreted as the maximum expected yield of crop *k* on farm *i*. This term depends on the natural endowment of the farm, on the production technology used by the farmer as well as on his ability.

Equation (5b) defines the acreage share optimal choices based on the expected profit maximization problem given by:

$$(6) \qquad \max_{(s_k:k\in\mathcal{K})\geq\mathbf{0}} \left\{ \sum_{k\in\mathcal{K}} s_k \pi_{k,it} - C_{it}(s_k : k\in\mathcal{K}) \text{ s.t. } \sum_{k\in\mathcal{K}} s_k = 1 \right\}.$$

The optimal acreage shares maximize the expected gross revenue of the farm, $\sum_{k\in\mathcal{K}} s_k \pi_{k,it}$, minus the implicit management costs of the acreage choice, $C_{it}(s_k : k\in\mathcal{K})$ under the total land use constraint, $\sum_{k\in\mathcal{K}} s_k = 1$. This constraint defines the crop 0 acreage share as the a function of the other acreage shares with $s_{0,it} = 1 - \sum_{k=1}^{K} s_{k,it}$. The implicit management cost function C_i plays a crucial role here. Under the assumption that it is strictly convex in the acreage share vector $(s_k : k\in\mathcal{K})$, it formally defines the diversification motive of the crop acreage. It is defined by Carpentier and Letort (2012, 2014) as the sum of the unobserved costs and the shadow costs related to binding constraints due to limiting quasi-fixed factor quantities or to bio-physical factors.[10] Since these endowments are highly heterogeneous, this cost function needs to be specified as farmer specific. The functional form of the acreage share models in equation system (5b) are obtained by choosing the following Nested MNL management cost function:

$$(7) \qquad \begin{aligned} C_{it}(s_k : k\in\mathcal{K}) = & \sum_{g\in\mathcal{G}} \sum_{k\in\mathcal{K}_g} s_k(\chi_{k,i} - u_{k,it}) \\ & + \alpha_i^{-1} \sum_{g\in\mathcal{G}} (1-\alpha_i\rho_{g,i}^{-1}) \bar{s}_g \ln \bar{s}_g + \sum_{g\in\mathcal{G}} \rho_{g,i}^{-1} \sum_{k\in\mathcal{K}_g} s_k \ln s_k \end{aligned}$$

[10] It can also be interpreted as a penalty function for deviations from some reference acreage vector for which the quasi-fixed factor endowment of the farm is best suited.

up to an additive fixed cost (Carpentier and Letort, 2014). The term $\overline{s}_g \equiv \sum_{k \in \mathcal{K}_g} s_k$ defines the acreage share of group *g*. The strict convexity of C_{it} is ensured if $\rho_{g,i} \geq \alpha_i > 0$ for $g \in \mathcal{G}$. All parameters of C_{it} are assumed to be farmer specific to ensure its ability to capture the heterogeneity of the farms' capital endowments (and of farmers' characteristics as is discussed below). The heterogeneity of the α_i and $\rho_{g,i}$ parameters plays a crucial role in this respect.[11] As shown by equation (5b), these terms largely determine the acreage choice elasticities. The larger they are, the more acreage choices of farmer *i* are responsive to economic incentives.

The $\chi_{k,i} - u_{k,it}$ terms represent short run fixed costs per unit of land of crop *k*. The $\chi_{k,i}$ terms are defined as random parameters capturing crop specific costs such as fixed costs per unit of land or unobserved variable costs of crop *k*. The $u_{k,it}$ terms are defined as centered error terms. These last terms capture the effects of random events occurring before the planting date and affecting the crop planting costs. The random parameter $\chi_{k,i}$ is part of the $\zeta_{k,i}$ parameter of the gross margin $\pi_{k,it}$ (see equation (5c) and Appendix A).

The interpretation of C_{it} given above relies on the theoretical background given in Carpentier and Letort (2014). In empirical applications, the parameters of this function may also capture the effects of other diversification motives of crop acreages. *E.g.*, it may partly capture the effects of risk spreading motives (Chavas and Holt, 1990) or of crop rotations (Howitt, 1995). This provides further arguments for its specification based on farm specific parameters. In

[11] The term $\rho_{g,i}$ equals α_i if group *g* is a singleton. *E.g.*, we have $\rho_{0,i} = \alpha_i$. If $\rho_{g,i} = \alpha_i$ for $g \in \mathcal{G}$ then equation (5b) reduces to the Standard MNL acreage share model and equation (11) reduces to the corresponding acreage management cost function.

particular, farmers may have heterogeneous attitudes toward risk, financial constraints or personal wealth levels. This basically implies that the empirical estimates of the C_{it} functions need to be interpreted as reduced form functions capturing various diversification acreage motives while accounting for the heterogeneity of the effects of these motives among the considered farmers' population.

Many multicrop models proposed in the literature use more flexible functional forms than the one considered here (see, *e.g.*, Chambers and Just, 1989 ; Oude Lansink and Peerlings, 1996 ; Moro and Skockai, 2006). As far as short run micro-economic choices are concerned, our viewpoint is that it may be more important to account for heterogeneity in the considered model than to use a highly flexible functional form for this model. Roughly speaking, if heterogeneity really matters it may be preferable to use a first order approximation for each sampled farm rather than to use a second order approximation defined at the sample level. Note also that the total land use constraints imply that the terms $\zeta_{k,i}$ and $u_{k,it}$ are defined up to an additive term. The terms $\zeta_{0,i}$ and $u_{0,it}$ are normalized at 0.[12]

Additional notations are required to present the distributional assumptions defining the parametric model considered in the empirical application. The following system level vectors are obtained from the corresponding crop level variables: $\mathbf{s}_{it} \equiv (s_{k,it} : k \in \mathcal{K})$, $\mathbf{y}_{it} \equiv (y_{k,it} : k \in \mathcal{K})$, $\mathbf{p}_{it} \equiv (p_{k,it} : k \in \mathcal{K})$, $\mathbf{v}_{it} \equiv (v_{k,it} : k \in \mathcal{K})$, $\mathbf{u}_{it} \equiv (u_{k,it} : k \in \mathcal{K} \setminus \{0\})$, $\boldsymbol{\beta}_i \equiv (\beta_{k,i} : k \in \mathcal{K})$, $\boldsymbol{\rho}_i \equiv (\rho_{g,i} : g \in \mathcal{G} \setminus \{0\})$, $\boldsymbol{\zeta}_i \equiv (\zeta_{k,i} : k \in \mathcal{K} \setminus \{0\})$, $\boldsymbol{\delta}_t \equiv (\delta_{k,t} : k \in \mathcal{K})$, and $\boldsymbol{\gamma} \equiv (\gamma_k : k \in \mathcal{K})$. The vector $\boldsymbol{\delta} \equiv (\boldsymbol{\delta}_k : t = 1,..,T)$ contains the year specific effects of the yield supply functions.

[12] These normalization constraints imply that the $\zeta_{k;,i}$ and $u_{k,it}$ terms are to be interpreted as differences with their counterparts for crop 0.

2.2. Mixing probability distribution density function and "kernel" likelihood function

In order to relate the multicrop model of this section with the generic choice model in the preceding section, we finally define the farmer choice vector $\mathbf{c}_{it} \equiv (\mathbf{y}_{it}, \mathbf{s}_{it})$, the exogenous variable vector $\mathbf{z}_{it} \equiv (\mathbf{p}_{it}, w_{it}, d_{it})$, the error term vector $\mathbf{e}_{it} \equiv (\mathbf{v}_{it}, \mathbf{u}_{it})$ and the random parameter vector $\mathbf{q}_i \equiv (\ln \boldsymbol{\beta}_i, \ln \alpha_i, \ln \boldsymbol{\rho}_i, \zeta_i)$. The exogenous variable vector $\mathbf{z}_{it}$ includes the year dummy variable d_t.

The response function **r** considered in the preceding section is given by equations (5). It is parameterized by the random parameter vector $\mathbf{q}_i$. The counterpart of **r** in the considered multicrop model is also parameterized by the fixed parameter vector $(\boldsymbol{\gamma}, \boldsymbol{\delta})$. As argued in the preceding section, the terms $\mathbf{z}_{it}$, $\mathbf{e}_{it}$ and $\mathbf{q}_i$ are assumed to be mutually independent for $t = 1, ..., T$. Provided that the stochastic events affecting the crop production process are unknown at the time acreage choices are made, it can be assumed that the terms $\mathbf{v}_{it}$ and $\mathbf{u}_{it}$ are also independent for $t = 1, ..., T$.

As is standard for error terms, $\mathbf{v}_{it}$ and $\mathbf{u}_{it}$ are assumed to be normal with $\mathbf{v}_{it} \sim \mathcal{N}(\mathbf{0}, \boldsymbol{\Lambda})$ and $\mathbf{u}_{it} \sim \mathcal{N}(\mathbf{0}, \boldsymbol{\Psi})$. The mixing distribution of the model is also assumed to be normal with $\mathbf{q}_i \sim \mathcal{N}(\mathbf{a}, \boldsymbol{\Omega})$. This probability distribution imposes no restriction on the relationships among the elements of $\mathbf{q}_i$. Due to the log transformation of $\boldsymbol{\beta}_i$, α_i and $\boldsymbol{\rho}_i$ in $\mathbf{q}_i$, these terms are indeed assumed to be jointly log-normal. This ensures their strict positivity.

Once again, in order to related the multicrop model considered here to the more general framework elements of the previous section, the fixed parameter vector $(\boldsymbol{\gamma}, \boldsymbol{\delta})$ and the distinct

elements of the parameters $\boldsymbol{\alpha}$, $\boldsymbol{\Lambda}$ and $\boldsymbol{\Psi}$ are collected in $\boldsymbol{\mu}$. The distinct elements of $\mathbf{a}$ and $\boldsymbol{\Omega}$ are collected in $\boldsymbol{\eta}$. Finally, $\boldsymbol{\theta} \equiv (\boldsymbol{\mu}, \boldsymbol{\eta})$ defines the "full" parameter vector to be estimated.

The inverse function of $\mathbf{r}$ is required to determine the likelihood functions of the considered model. The elements of $\mathbf{v}_{it}$ can easily be recovered from equation (5a) while the elements of $\mathbf{u}_{it}$ can be obtained by application of Berry's (1994) device:

$$
\begin{aligned}
u_{k,it} = \alpha_i^{-1} \times \Big[& \ln s_{k,it} - \ln s_{0,it} - (1 - \alpha_i \rho_{g,i}^{-1}) \times (\ln s_{k,it} - \ln \overline{s}_{g,it}) \Big] \\
& + \zeta_{k,i} - p_{k,it} (\beta_{k,i} + \overline{\delta}_k) - 1/2 \times \gamma_k w_{it}^2 p_{k,it}^{-1} + p_{0,it} (\beta_{0,i} + \overline{\delta}_0) + 1/2 \times \gamma_0 w_{it}^2 p_{0,it}^{-1}
\end{aligned} \tag{8}
$$

if $k \in \mathcal{K}_g$.

The density of $\mathbf{c}_i$ conditional on $(\mathbf{z}_i, \mathbf{q}_i)$ can be obtained by applying equation (2) and by using the density of normal random vectors. Let $\varphi(\mathbf{u}; \mathbf{B})$ denote the probability density function of $\mathcal{N}(\mathbf{0}, \mathbf{B})$ at $\mathbf{u}$. The density of $\mathbf{y}_{it}$ conditional on $(\mathbf{z}_i, \mathbf{q}_i)$ is given by:

$$
f(\mathbf{y}_{it} \mid \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\mu}) = \varphi(\mathbf{v}_{it}; \boldsymbol{\Lambda}) \tag{9a}
$$

and that of $\mathbf{s}_{it}$ conditional on $(\mathbf{z}_i, \mathbf{q}_i)$ is given by:

$$
f(\mathbf{s}_{it} \mid \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\mu}) = \alpha_i^{-G} \left(\prod\nolimits_{g \in \mathcal{G}} \rho_{g,i}^{1-K_g} \right) \left(\prod\nolimits_{k \in \mathcal{K}} s_{k,it}^{-1} \right) \times \varphi(\mathbf{u}_{it}; \boldsymbol{\Psi}) . \tag{9b}
$$

The mutual independence of $\mathbf{v}_{it}$ and $\mathbf{u}_{it}$ conditional on $(\mathbf{z}_i, \mathbf{q}_i)$ for $t = 1, ..., T$ yields:

$$
f(\mathbf{c}_{it} \mid \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\mu}) = f(\mathbf{y}_{it} \mid \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\mu}) \, f(\mathbf{s}_{it} \mid \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\mu}) \tag{9c}
$$

Finally, the random parameter vector density is given by:

$$
h(\mathbf{q}_i; \boldsymbol{\eta}) = \varphi(\mathbf{q}_i - \mathbf{a}; \boldsymbol{\Omega}) . \tag{9d}
$$

3. Estimation

Estimation of a random parameter model such as the one presented in the preceding section requires specific estimators due to its specific structure. From a theoretical viewpoint, the

parameters of this fully parametric model can be efficiently estimated according to the ML principle. But the ML estimator of $\boldsymbol{\theta}$ is practically "infeasible" because the individual likelihood functions, *i.e.* the $f(\mathbf{c}_i \mid \mathbf{z}_i;\boldsymbol{\theta})$ terms given in equation (3), cannot be integrated in our case, neither analytically, nor numerically. These likelihood functions must be integrated with simulation methods, implying that the estimators of $\boldsymbol{\theta}$ must be simulated counterparts of the standard ML estimator.

Furthermore, maximizing the "true" sample log-likelihood function, *i.e.* $\sum_{i=1}^{N} \ln f(\mathbf{c}_i \mid \mathbf{z}_i;\boldsymbol{\theta})$, in $\boldsymbol{\theta}$ would be very difficult in practice, due to the functional form of the individual likelihood functions and due to the dimension of $\boldsymbol{\theta}$. Specific extensions of the Expectation-Maximization (EM) algorithm of Dempster *et al* (1977) have been proposed in the statistics literature to compute the ML estimators of random parameter models with continuous mixing probability distributions. We employ a Simulated EM (SEM) algorithm to compute an estimator whose asymptotic properties are basically those of the infeasible ML estimator of $\boldsymbol{\theta}$ (see, *e.g.*, McLachlan and Krishnan (2008) for a recent review of the numerous SEM algorithms proposed in the statistics literature).

This section presents the main features of our computation strategy for estimating $\boldsymbol{\theta}$. The particular design of the SEM algorithm we use was mainly based on practical considerations. Other SEM algorithms may be more efficient from a numerical viewpoint or may require less computing time. But this algorithm is relatively easy to code, has good theoretical properties and seems to perform well in practice, at least as far as our limited experience proves this.

Our estimators are built by approximating $f(\mathbf{c}_i \mid \mathbf{z}_i;\boldsymbol{\theta})$ with simulation methods. Provided that the $\tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta})$ terms are independent random draws from $h(\mathbf{q};\boldsymbol{\eta})$ for $s = 1,...,S$, the simulated term:

$$(10) \qquad \tilde{f}_S(\mathbf{c}_i \mid \mathbf{z}_i;\boldsymbol{\theta}) \equiv S^{-1} \sum_{s=1}^{S} f(\mathbf{c}_i \mid \mathbf{z}_i, \tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta});\boldsymbol{\mu})$$

is a consistent simulator of $f(\mathbf{c}_i \mid \mathbf{z}_i;\boldsymbol{\theta})$ whose accuracy increases in *S*. While econometricians usually employ Simulated ML (SML) estimators in this context, statisticians usually prefer to rely on SEM algorithms. These algorithms allow computing estimators which differ from SML estimators but which basically share the same asymptotic properties as *S* and *N* grows to infinity, with *S* rising faster than $N^{1/2}$ (Jank and Booth, 2003). The SML estimator of $\boldsymbol{\theta}$ is obtained by directly maximizing the sample simulated log-likelihood function $\ln \tilde{L}_{S,N}(\boldsymbol{\theta}) \equiv \sum_{i=1}^{N} \tilde{f}_S(\mathbf{c}_i \mid \mathbf{z}_i;\boldsymbol{\theta})$. This maximization problem is intractable in our application. The dimension of $\boldsymbol{\theta}$ is quite large and $\ln \tilde{L}_{S,N}(\boldsymbol{\theta})$ is highly non linear in $\boldsymbol{\theta}$.[13]

3.1. Basic EM algorithm

The EM algorithm is particularly well suited for computing ML estimators in cases where the model of interest involves hidden variables such as random parameters. It consists in iterating two steps, the Expectation step (E step) and the Maximization step (M step), until numerical convergence. It basically replaces a large ML problem by a sequence of simpler maximization problems.[14]

In our case the EM algorithm involves the following density:

(11) $\kappa(\mathbf{c}_i, \mathbf{q}_i \mid \mathbf{z}_i;\boldsymbol{\theta}) \equiv f(\mathbf{c}_i \mid \mathbf{z}_i, \mathbf{q}_i;\boldsymbol{\mu}) h(\mathbf{q}_i;\boldsymbol{\eta})$.

[13] *E.g.*, Train (2009) reports that the variance matrix of Gaussian mixing probability distribution is not easily recovered by SML estimators, leading to the restriction that this matrix is diagonal or block-diagonal in many empirical studies.

[14] The EM algorithm also increases the sample log-likelihood at each iteration, implying that it generally leads to a (local) maximum of the considered likelihood function. SEM algorithms do not necessarily monotonically increase the simulated sample log-likelihood due to the simulation noise. The main drawback of the EM algorithm is that, albeit it moves quickly into the neighborhood of ML estimator of $\boldsymbol{\theta}$, it numerically converges slowly within this neighborhood.

The term $\kappa(\mathbf{c}_i, \mathbf{q}_i \mid \mathbf{z}_i; \boldsymbol{\theta})$ is the probability density function of the "complete" dependent variable vector $(\mathbf{c}_i, \mathbf{q}_i)$ conditional on the exogenous variable $\mathbf{z}_i$. As a result $\ln \kappa(\mathbf{c}_i, \mathbf{q}_i \mid \mathbf{z}_i; \boldsymbol{\theta})$, is the log-likelihood function at $\boldsymbol{\theta}$ of $(\mathbf{c}_i, \mathbf{q}_i)$ conditional on $\mathbf{z}_i$. At iteration *n*, provided that $\boldsymbol{\theta}_{n-1}$ is the value of $\boldsymbol{\theta}$ obtained at the end of iteration $n-1$, the EM algorithm iterates the following steps until numerical convergence:

E step. Integration of the conditional expectations

(12a) $E[\ln \kappa(\mathbf{c}_i, \mathbf{q}_i \mid \mathbf{z}_i; \boldsymbol{\theta}) \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}_{n-1}] \equiv \int \ln \kappa(\mathbf{c}_i, \mathbf{q} \mid \mathbf{z}_i; \boldsymbol{\theta}) h(\mathbf{q} \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}_{n-1}) d\mathbf{q}$ for $i = 1, \ldots N$.

M step. Update of the value of $\boldsymbol{\theta}$

(12b) $\boldsymbol{\theta}_n \equiv \arg\max_{\boldsymbol{\theta}} Q_N(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1})$ where $Q_N(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1}) \equiv \sum_{i=1}^{N} E[\ln \kappa(\mathbf{c}_i, \mathbf{q}_i \mid \mathbf{z}_i; \boldsymbol{\theta}) \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}_{n-1}]$.

The E step thus consists in integrating the individual log-likelihood functions $\ln \kappa(\mathbf{c}_i, \mathbf{q}_i \mid \mathbf{z}_i; \boldsymbol{\theta})$ over the *ex post* density $h(\mathbf{q} \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}_{n-1})$. This integration yields the expectation of log-likelihood function at $\boldsymbol{\theta}$ of the "complete" dependent variable vector of farmer *i* conditional on what is known on this farmer, *i.e.* $(\mathbf{z}_i, \mathbf{c}_i)$, and assuming that $\boldsymbol{\theta}_{n-1}$ is the true value of the interest parameter. The updated value of $\boldsymbol{\theta}_n$ is then defined as an ML estimator of based on the individual expected log-likelihood functions computed in the E step.

Equation (11) is specific to models involving hidden variables. It is used to split the M step into two maximization problems:

(13a) $\boldsymbol{\mu}_n \equiv \arg\max_{\boldsymbol{\mu}} \sum_{i=1}^{N} E[\ln f(\mathbf{c}_i \mid \mathbf{z}_i, \mathbf{q}_i; \boldsymbol{\mu}) \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}_{n-1}]$

and:

(13b) $\boldsymbol{\eta}_n \equiv \arg\max_{\boldsymbol{\eta}} \sum_{i=1}^{N} E[\ln h(\mathbf{q}_i; \boldsymbol{\eta}) \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}_{n-1}]$

where $\boldsymbol{\theta}_n \equiv (\boldsymbol{\mu}_n, \boldsymbol{\eta}_n)$. The parameters of the "behavioral model" on the one hand, and those of the "mixing" probability distribution model on the other hand can be separately updated. Moreover, as is shown below, to solve the maximization problems involved in equations (13) is much simpler than to maximize the corresponding simulated log-likelihood function $\ln \tilde{L}_{S,N}(\boldsymbol{\theta})$.

3.2. Simulation methods: SEM algorithms

The EM algorithm described above would lead to the ML estimator of $\boldsymbol{\theta}$ but it cannot be implemented. The expectations in equations (12)–(13) cannot be computed neither analytically, nor numerically. The SEM algorithms were proposed to extend the use of the EM algorithms in cases where the E step requires integration by simulation methods.[15] The expectations in equation (13) were integrated by a importance sampling simulator proposed by Caffo *et al* (2005) or Train (2007, 2008). This simulator, later designated as the "*ex Ante*/*ex Post*" Importance Sampling (APIS) simulator , was used to estimate the conditional expectations in equations (12)–(13) as well as to calibrate the farmer's specific parameters in our empirical application. It allows integrating any function of $(\mathbf{q}_i, \mathbf{z}_i, \mathbf{c}_i)$, say $\boldsymbol{\tau}_i(\mathbf{q}_i) \equiv \boldsymbol{\tau}(\mathbf{q}_i, \mathbf{z}_i, \mathbf{c}_i)$, over the *ex post* density of the random parameters $h(\mathbf{q}_i \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta})$ by only using independent random draws of $\mathbf{q}_i$ from the *ex ante* density $h(\mathbf{q}; \boldsymbol{\eta})$, *i.e.* by simply using the $\tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta})$ draws. Equation (5) allows showing that

$$(14) \qquad E[\boldsymbol{\tau}_i(\mathbf{q}_i) \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}] \equiv \int \boldsymbol{\tau}_i(\mathbf{q}) h(\mathbf{q} \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}) d\mathbf{q} = \int \omega_i(\boldsymbol{\theta}) \boldsymbol{\tau}_i(\mathbf{q}) h(\mathbf{q}; \boldsymbol{\eta}) d\mathbf{q} .$$

It is then easily seen that

[15] Note that equations (3) and (4) show that the integration problems encountered either when using the EM algorithm or when considering direct ML procedures have the same root, *i.e.* it is difficult to compute $h(\mathbf{q}_i \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta})$ because it is difficult to compute $f(\mathbf{c}_i \mid \mathbf{z}_i; \boldsymbol{\theta})$.

(15) $S^{-1}\sum_{s=1}^{S}\tilde{\omega}_{i,s}(\boldsymbol{\theta})\boldsymbol{\tau}_i\left(\tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta})\right)$ where $\tilde{\omega}_{i,s}(\boldsymbol{\theta}) \equiv \dfrac{f\left(\mathbf{c}_i \mid \mathbf{z}_i, \tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta}); \boldsymbol{\mu}\right)}{S^{-1}\sum_{s=1}^{S} f\left(\mathbf{c}_i \mid \mathbf{z}_i, \tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta}); \boldsymbol{\mu}\right)}$

is a consistent simulator of $E[\boldsymbol{\tau}_i(\mathbf{q}_i) \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}]$. The APIS simulator allows approximating the objective function in equation (13b) by

(16.a) $H_{S,N}(\boldsymbol{\eta} \mid \boldsymbol{\theta}_{n-1}) \equiv N^{-1}\sum_{i=1}^{N} S^{-1}\sum_{s=1}^{S}\tilde{\omega}_{i,s}(\boldsymbol{\theta}_{n-1}) \ln h\left(\tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta}_{n-1}); \boldsymbol{\eta}\right)$.

Given the panel structure of the data the objective function in equation (13a) can be approximated by

(16.b) $F_{S,N}(\boldsymbol{\mu} \mid \boldsymbol{\theta}_{n-1}) \equiv N^{-1}\sum_{i=1}^{N} S^{-1}\sum_{s=1}^{S}\sum_{t=1}^{T}\tilde{\omega}_{i,s}(\boldsymbol{\theta}_{n-1}) \ln f\left(\mathbf{c}_{it} \mid \mathbf{z}_{it}, \tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta}_{n-1}); \boldsymbol{\mu}\right)$.

To (separately) maximize the functions $H_{S,N}(\boldsymbol{\eta} \mid \boldsymbol{\theta}_{n-1})$ and $F_{S,N}(\boldsymbol{\mu} \mid \boldsymbol{\theta}_{n-1})$ in $\boldsymbol{\eta}$ and $\boldsymbol{\mu}$ is much easier than to directly maximize the simulated log-likelihood function

(17) $\ln \tilde{L}_{S,N}(\boldsymbol{\theta}) = N^{-1}\sum_{i=1}^{T} \ln\left(S^{-1}\sum_{s=1}^{S}\prod_{t=1}^{T} f\left(\mathbf{c}_i \mid \mathbf{z}_i, \tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta}); \boldsymbol{\mu}\right)\right)$

in $\boldsymbol{\theta} \equiv (\boldsymbol{\eta}, \boldsymbol{\mu})$.

Our estimates were computed by using an algorithm in the class of the SEM algorithms proposed by Delyon *et al* (1999). These algorithms, designated as the Stochastic Approximation EM (SAEM) algorithms, have two main advantages. First, they are numerically stable despite their requiring integrations by simulation methods at each of their iterations.

Second, SAEM algorithms allow using simplified versions of the M step. In the M step given in equation (12b) $\boldsymbol{\theta}_n$ is assumed to maximize $Q_N(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1})$. Indeed, $\boldsymbol{\theta}_n$ can just be selected as a value of $\boldsymbol{\theta}$ such that $Q_N(\boldsymbol{\theta}_n \mid \boldsymbol{\theta}_{n-1}) > Q_N(\boldsymbol{\theta}_{n-1} \mid \boldsymbol{\theta}_{n-1})$, if possible. We used the simplification of the M step proposed by Meng and Rubin (1993), *i.e.* the sequence of

Conditional Maximization (CM) steps of their Expectation–Conditional Maximization (ECM) algorithm.

We finally end up with a SEM algorithm for which the elements of $\boldsymbol{\eta}_n$ are computed as weighted empirical means and covariances whereas the elements of $\boldsymbol{\mu}_n$ are defined as weighted empirical covariances or as weighted Feasible Generalized Least Squares estimators. A detailed presentation of our algorithms is provided in Appendix B.

3.3. Identification issues

The multicrop model presented in the preceding section basically is a standard multicrop model with random parameters. It is composed of two equations sub-systems, the yield supply equations sub-system and the acreage choice equations sub-system. This specific structure of our model is exploited for designing the SAEM algorithm discussed above (see also Appendix B). The parameters of the yield supply equations sub-system – *i.e.* $\boldsymbol{\gamma}$, $\boldsymbol{\delta}$, $\boldsymbol{\Lambda}$, and the mean and variance of $\boldsymbol{\beta}_i$ – can be estimated separately. This is a system of regression equations with random individual effects (see, *e.g.*, Biorn 2004). The likelihood function of the acreage choice equations sub-system depends on the parameters of yield supply equations sub-system and allows estimating $\boldsymbol{\Psi}$, the parameters of the probability distribution of the remaining random parameters – *i.e.* the mean and variance of $(\alpha_i, \boldsymbol{\rho}_i, \zeta_i)$ – as well as the covariance of these parameters with $\boldsymbol{\beta}_i$.

Two identification issues arise in our empirical application. These mostly come from the fact that netput prices mainly vary across time while we only consider a short time period. This implies that price effects ($\boldsymbol{\gamma}$) can hardly be distinguished from time-related effects ($\boldsymbol{\delta}$) in the yield equations. We decided to keep the price effects in the yield supply equation specification

because their empirical estimates are quite small, as expected (see, *e.g.*, Scott (2013) for a discussion on the estimation of yield price elasticities). Introduction of variables capturing the effects of climatic events would only partly solve the problem as the year specific parameters may also capture the technological progress embodied in seeds or in cropping practices.

The probability distribution of the farm specific parameters of the acreage management cost function $(\alpha_i, \boldsymbol{\rho}_i, \boldsymbol{\zeta}_i)$ is identified by the variations of $p_{\ell,it} \times (\beta_{\ell,i} + 1/2 \times \gamma_\ell w_{it}^2 p_{\ell,it}^{-2})$ in the crop gross margins given in equation (5c). Since the variations in the $(\mathbf{p}_{it}, w_{it})$ prices are limited, identification of the probability distribution of $(\alpha_i, \boldsymbol{\rho}_i, \boldsymbol{\zeta}_i)$ largely relies on the variations of the $\boldsymbol{\beta}_i$ terms. Of course the probability distribution of $\boldsymbol{\beta}_i$ is identified by the yield supply equations sub-system. But, the choice of the "mixing" probability distribution, *i.e.* the choice of the probability density function of $(\boldsymbol{\beta}_i, \alpha_i, \boldsymbol{\rho}_i, \boldsymbol{\zeta}_i)$, partly ensures the identification of the probability distribution of $(\alpha_i, \boldsymbol{\rho}_i, \boldsymbol{\zeta}_i)$. This distributional assumption implicitly constrains the functional form of the correlation between $\boldsymbol{\beta}_i$ and $(\alpha_i, \boldsymbol{\rho}_i, \boldsymbol{\zeta}_i)$. Hence, the parametric probability density function $h(\mathbf{q}_i; \boldsymbol{\eta})$ partly ensures the identification of the characteristics of the probability distribution of $(\alpha_i, \boldsymbol{\rho}_i, \boldsymbol{\zeta}_i)$, according to an "identification by functional forms" mechanism.

As a matter of fact, the identification issues discussed here are not specific to our application. The main observed exogenous factors affecting agricultural production choices are the netput prices. But these mainly vary across time.[16] As a result, identification of the characteristics of the probability distribution of the random parameters with proper "exogenous variables variations" would require observations covering larger periods. But in this case the probability distribution of the random parameters could not be assumed to be constant along the

[16] Notwithstanding that this variation may be due to netput quality effects.

considered period because farmers' technology choices and quasi-fixed factor endowments are impacted by netput prices.

4. Empirical application

As an illustrative application of the approach proposed in this paper to account for farm heterogeneity, we use a set of French data to estimate the multicrop model presented in the second section. These estimations allow an investigation of the distribution of the random parameters of the model, which comes to illustrate the importance of unobserved heterogeneity in farmers' production choices. Based on these estimation results, we perform a "statistical calibration" of the model parameters for each sampled farmer in order (*i*) to evaluate the performances of the estimated model and (*ii*) to reveal some potential determinants of the heterogeneity in farmers' behaviors. We then perform some simulations in order to study the impacts and potential implications of the modeling of heterogeneous behaviors on simulation results.

4.1. Data

The data set used to estimate our model is a panel data sample of 391 observations of French grain crop producers in the large (geological) Paris basin over the years 2004 to 2007, obtained from the Farm Accountancy Data Network (FADN). It provides detailed information on crop production for each farm: acreage, yield and price at the farm gate. The aggregated input price index is made available at the regional level by the French Department of Agriculture.

In our application yield levels and acreage share choices are considered for three (aggregated) crops: soft wheat (crop 1), other cereals (mainly barley and corn, crop 2) and, oilseeds (mainly rapeseed) and protein crops (mainly peas) (crop 0). Crop aggregates are

based on agronomic considerations. The basic rotation scheme of the French grain producers is a sequence with three crops as: rootcrops (*e.g.* potato or sugar beet) or protein crop or oilseed (*e.g.* rapeseed or sunflower) – winter wheat – secondary cereal (*e.g.* barley or wheat). This scheme is adapted to soil and climatic conditions. Rootcrops require good quality soils which are found in the north of France. Sunflower is grown in the south of France while rapeseed, the other main oilseed crop is grown in the north half of France (our region of interest). Sugar beet and potato acreages were considered exogenous due to production quotas for sugar beet and production contracts for potatoes.

The considered sample only includes observations with strictly positive acreages. This selection rule doesn't lead to significant attrition thanks to the crop aggregation procedure. Our sample covers the French regions specialized in grain production, with the notable exception of the south-west of France where corn monoculture is the dominant cropping system. The 108 farms of our sample are observed for 3 or 4 years. We assume that farms' attrition is exogenous because the French FADN is constructed as a rotating panel seeking to collect data for 4 years for each sampled farm. Such an exogenous attrition is easily accommodated in our modeling framework. Farms' likelihood functions are computed according to the observed choice sequences.

4.2. Estimation Results

Our estimations were conducted by using the SAS software (IML procedure). The recursive step of simulation of SAEM algorithm was implemented using 1000 draws. The algorithm converged without difficulties after 244 iterations. Results were not significantly affected by the use of alternative starting values or by the use of larger number of draws.

Selected estimation results are reported in Table 1 and Table 2, the complete results being available from the authors upon request. These results show that the model fits relatively well to the data. Indeed, most parameters, especially the expectations and covariances of the random parameters $\mathbf{q}_i$ and the variance matrices of the error terms appear to be precisely estimated. The fixed parameters representing price ($\boldsymbol{\gamma}$) and time ($\boldsymbol{\delta}$) effects appear to be less precisely estimated. This is due to the lack of variation in the netput prices in our sample as discussed above. This identification issues do not have a significant impact on the estimation of the other parameters of the model. The price effects captured by the $\boldsymbol{\gamma}$ parameters are fairly limited when compared with those represented by the year effects $\boldsymbol{\delta}$. Indeed, results similar to the ones presented here were obtained for a model ignoring the price effects in the yield equations.

The probability distribution of the yield equations random parameters (reported in Table 1) is precisely estimated. This was expected since each yield equation basically is a regression equation with individual random terms. The parameter estimates lie in reasonable ranges. The estimates of the probability distribution of $\boldsymbol{\beta}_i$ show that the $\beta_{k,i}$ parameters significantly vary across farms while being strongly positively correlated to each other. This was expected because yield potentials vary across regions, and because good growing conditions for a grain crop are also good for the others. The variance of $\beta_{k,i}$ is higher or close to that of $v_{k,it}$ for wheat and other cereals, but the variance of $v_{k,it}$ is twice that of error terms in the oilseeds case. This may reflects at least two points: first, a large part of the heterogeneity in cereals, and notably wheat, yields is due differences in unobservable characteristics of each farm or farmer; second, provided that rapeseed is by far the most important oilseed in northern

France, these results may be due to the fact that the rapeseed yield is more risky than the cereal yield, mostly due to bugs and diseases, and due to its sensitivity to climatic conditions.

The acreage share equation parameter estimates (reported in Table 2) also range in reasonable ranges. The estimated mean of $\ln \alpha_i$, respectively of $\ln \rho_i$, equals –2.357, respectively –2.186. Importantly, the estimate of the mean of ρ_i is higher than that of α_i. This is a sufficient condition for the entropic acreage management cost function, lying at the root of the Nested MNL acreage share function, to be convex. According to the estimates of their respective variances, the α_i and ρ_i parameters significantly vary across farms. This result is important for simulation studies because these parameters largely determine acreage price elasticities in MNL acreage share models. The higher α_i and ρ_i are, the more reactive the acreages are to price changes. The elements of $\boldsymbol{\beta}_i$ appear to be positively correlated with α_i. A possible interpretation of this result is as follows. High levels of $\boldsymbol{\beta}_i$ indicate good farming conditions for grain crops in farm i and/or farmer i technical ability. This implies that the farm operation is sufficiently profitable to allow suitable machinery investments which, in turn, implies a high level of α_i and, finally, relatively unconstrained acreage choices between cereals and oilseeds. The results are different when it comes to acreage adjustments within the cereal nest: the elements of $\boldsymbol{\beta}_i$ are not positively correlated with ρ_i, which tends to show that the flexibility of acreage adjustments between wheat and other cereals is associated to other factor than the one advocated previously.

4.3. Statistical calibration of individual parameters

As explained in the first part of the paper, the estimated parametric model allows a computation of the (random) $\mathbf{q}_i$ parameters for each farm/farmer of the sample, according to the logic “tell me what you do, I'll tell you who you are”. Once the *ex ante* distribution of $\mathbf{q}_i$

in the population has been estimated we “statistically calibrate” the specific parameters for each individual i based on the *ex post* density of $\mathbf{q}_i$. This is easily done by applying equation (15) with $\boldsymbol{\tau}_i(\mathbf{q}_i) = \mathbf{q}_i$. The *ex post* and *ex ante* density of the random parameters $\boldsymbol{\beta}_i$, α_i and ρ_i are represented on Figure 1. The two distributions almost superimposed for all parameters, which reflects a good specification of our model (Train, 2007). We can also notice that the distributions of the $\boldsymbol{\beta}_i$ parameters, representing maximum potential yields of the farms, appear to be more spread for other cereals than for the two other crops, reflecting a higher heterogeneity of yields between farms for that crop. That might be due to the fact that “other cereals” is an aggregate of various crops (mainly corn and barley), whereas “wheat” is a single crop and “oilseeds” is essentially composed of rapeseed in our sample. The probability distributions α_i and ρ_i reflects the fact that α_i parameters generally take lower values than ρ_i parameters (this is actually the case for 73% of the farms/farmers, the remaining 27% individuals having ρ_i values almost equal to α_i values), which reflects more flexible adjustments between wheat and other cereal acreages than between oilseeds and other crops and is a sufficient condition for the acreage management cost function to be convex. Figure 2 reports the calibrated values of the $\boldsymbol{\beta}_i$, α_i and ρ_i parameters together with their confidence intervals for each farm/farmer of the sample. We can see from these graphs that confidence intervals of parameters do not overlap for all individuals: these parameters do actually take different values from one individual to another. This comes to illustrate the heterogeneity in potential yields across farms and in the way farmers are able to adjust their acreages in response to economic incentives.

Having calibrated individual parameters for each farm/farmer, we are able to compute the individual yields and acreages predicted by the NMNL model.

Based on these predictions, we can then compute "pseudo R^2" criteria corresponding to the share of the variance of interest variables predicted by the model, and compare the observed values of these variables to their predicted values. The fitting criteria of the model are reported in Table 3 below. Once again, the model proves to fit well the data, especially for wheat and other cereals with "pseudo R^2" around 60% for yields and 70% for acreage shares.

Up to this point, our estimation results have shown that farmers' behaviors do actually rely on heterogeneous factors. It thus seems crucial to account for heterogeneity in micro econometric production choice models. If the sources of this heterogeneity were known to econometricians, they could be controlled for through, *e.g.* the use of control variables.[17] However, if some of them are identifiable, heterogeneity sources are multiple and most of them can certainly not be reduced to farm/farmers' observable characteristics.

This point is illustrated by Figure 3 and Table 4. Maps reported on Figure 3 show the calibrated values of three parameters: $\beta_{k,i}$ for wheat, α_i and ρ_i[18] for each farm of our sample. The top left map clearly shows that the distribution of potential wheat yields exhibits a spatial pattern, the highest yields being located in the North of France. This is in total accordance with what is known about the different agronomic potentials of French regions. Introducing spatial farm characteristics in the model could help accounting for some heterogeneity. Farms' localization is however not the only source of heterogeneity in agricultural production choices. This is reflected by the two other maps on Figure 3: the distribution of the α_i and ρ_i parameters across space is different from that of the $\beta_{k,i}$ parameters. No specific spatial pattern seems emerge from these maps.

[17] Of course the use of control variables is allowed in our modeling approach. But it is omitted for simplicity as well as for investigating the potential of random parameter models.

[18] Maps corresponding to other parameters are available from the authors upon request

In a further attempt to qualify the potential sources of farmers' behavior heterogeneity, we have computed the correlations between the individual parameters and some observable farms/farmers characteristics considered as exogenous in the model: the amount of farm capital, the root crops acreage and the age of farmer[19]. These correlations are reported in Table 4. Farm capital is positively and significantly correlated with the $\beta_{k,i}$ parameter for oilseed, the α_i parameter, and to a lesser extent the $\beta_{k,i}$ parameter for wheat. This reflects one argument previously advocated: farms endowed with more capital are the more productive ones and also own enough machinery to easily adjust their acreages. Different explanations can lie at the root of the positive and significant correlations between root crop acreage and the $\beta_{k,i}$ and α_i parameters: root crops are good preceding crops for wheat and other cereals which explains the positive correlation with their potential yields; furthermore, a good soil quality is necessary to grow root crops and this good quality also benefits to other crops like wheat and other cereals but also oilseeds, hence the positive correlation with all the $\beta_{k,i}$ parameters; finally, root crops can be used as an alternative to oilseeds as preceding crops for wheat and other cereals and thus relax some constraints on acreage adjustments which translates into a positive correlation with the α_i parameters. The positive and significant correlations between farmers' age and potential yields might be due to the role played by experience in farmers' skills and abilities, or by generational differences in the intensity of inputs, notably pesticides, use. All the aforementioned exogenous variables could thus help controlling for part of farm heterogeneity in our production choice model. However, none of the correlations presented in Table 4 is high enough to conclude that using these control variables would be sufficient to capture all the sources of heterogeneity.

[19] Other variables such as the number of labor hours or the total acreage of the farm have been tested but none of them were significantly correlated to any of the individual parameters.

4.4. Simulation Results

This last subsection is devoted to the presentation of some simulation results: we simulate the impacts of changes in crop prices corresponding to those that have been observed in France since 2007, namely a 20% in wheat and other cereal prices and a 50% increase in oilseeds prices. As mentioned earlier, the γ and δ parameters representing the effects of price and time on yields are not very precisely estimated. Therefore, we focus here on the impacts of price changes on acreages and assume that these shocks do not impact yields, which are thus held constant in the simulations.

Table 5 reports the distribution characteristics of the elasticities of acreages to changes in crops prices in our sample. These elasticities are key parameters determining farmers' responses to price shocks. We can first notice that all these calibrated elasticities have the expected signs: own price elasticities are positive and cross price elasticities are negative. They also lie in a reasonable range and reflect the higher flexibility of acreage adjustments within the cereal nest: wheat (respectively other cereals) acreage responds more to a change in other cereals (respectively wheat) price than to a change in oilseed price. Furthermore, the reported quantile values reflect a significant dispersion of elasticities within our sample. One can thus expect each farmer to react differently to the price changes we simulate here, which is not surprising given the variances of the model random parameters.

The first column of Table 6 reports the effects on acreages of the changes in crop prices simulated using our "statistically calibrated" individual parameters model. The relative increase of oilseeds price compared to wheat and other cereals prices lead farmers to reallocate part of their land to this now more profitable crop: among the 10168 ha devoted to crops in our sample, 159 ha of wheat (representing 4% of the initial wheat acreage) and 183 ha of other cereals (representing 6% of the initial other cereals acreage) are reallocated to

oilseeds which acreage thus increases by 342 ha (representing 12% of the initial oilseeds acreage). This represents average variations of 2 ha, 2 ha and 4 ha for respectively wheat, other cereals and oilseeds acreage. However, these variations significantly vary from one farm to another: the increases in oilseeds acreage notably vary between 1 ha and 13 ha in absolute term, and between 3% and 38% of the initial oilseeds acreage, depending on the farm. These contrasting results come to illustrate the heterogeneity in farmers' response to economic incentives.

In order to further assess the potential impacts of the approach proposed here to account for heterogeneity on the overall simulated effects of price changes, two alternative versions of the NMNL model have been estimated and used to simulate the same shock. In the first model, all parameters are fixed. This model is estimated using a standard ML approach. In the second model, the α and ρ parameters, representing the flexibility of acreages adjustment, are fixed, the $\boldsymbol{\beta}_i$, and ζ_i are random. This last model can thus be considered as fixed individual effect model. It is estimated using the SAEM algorithm. The estimation results of these two models are not presented here due to space limitation but are available upon request. Two main elements come out of these results. (*i*) In the fixed effect model, the estimated values of α and ρ are closed to estimated their means in the random parameter model with 0.100 for α and 0.122 for ρ. This is not the case with the fixed parameter model where the estimate value of α equals 0.017 while that of ρ equals 0.045. (*ii*) The log likelihood of the fixed effect and fixed parameter model respectively equal to –1005.4 and –940.27, compared to –816.35 for the random parameter model. The likelihood ratio test thus clearly indicates that the random parameter model significantly better fits the data than the fixed parameter model (378 for the test value with 28 restrictions) and the fixed effect model (248 for the test value with 13 restrictions) at the 1% level.

The impacts of price changes on acreages simulated with these two models are reported in the second and third column of Table 6. The overall impacts on acreages are clearly underestimated with the fixed parameter model: the changes in wheat, other cereals and oilseeds acreages are respectively equal to –44 ha, –3 ha and +48 ha, which represent 72% to 98% lower effects than the ones simulated with random parameter model. This can certainly essentially be attributed to the lower estimated values of α and ρ. However, despite $\hat{\alpha}$ and $\hat{\rho}$ values close to their "expectation equivalent" in the fixed effect model, overall simulated impacts also tend to be underestimated in this model, even if to a lesser extent (2% to 40% lower effects). These results are clearly illustrated on Figure 4 which reports the individual simulated effects on oilseeds acreage using the three models and taking the random parameter model as reference: the higher the impacts on oilseeds acreages are, the more they are underestimated by the two alternative models. There is thus a risk, by partially or totally ignoring the heterogeneous determinants of farmers' behaviors in micro econometric models, to generate biased simulation results.

Concluding remarks

Many unobserved heterogeneous factors can impact farmers' production decisions. The approach we propose in this paper allows accounting for this heterogeneity in the econometric estimations of agricultural production models in a fairly flexible way. We rely on a random parameter modeling framework: the distribution of the model parameters across the farmer population is estimated, which allows the parameters to be farmer specific in order to account for unobserved heterogeneity effects.

Using specific estimators and optimization procedures designed by statisticians, we are able to estimate a random version of the multicrop econometric model proposed by Carpentier and Letort (2014). This empirical application is based on a sample of French crop producers

observed from 2004 to 2007. We find that the key parameters of the model exhibit significant variability across farmers. Furthermore, our random model proves to better fit the data than its counterpart fixed or “quasi-fixed” versions. We thus find evidence that heterogeneity significantly matters for the modeling of micro-economic agricultural production choices.

We also show how random parameter models can be used to “statistically calibrate” a simulation model based on a sample of heterogeneous farms and use this “calibrated” model to simulate the impact of crop price changes on acreages. This allows us to further illustrate the potential role of heterogeneity in micro econometric production choices models, and to show that ignoring it can lead to misleading simulation results.

Of course, our empirical framework has many limitations calling for improvement and further research.

The limited size of the sample we consider is an issue. This sample was selected so as to only contain farms highly specialized in grain production, *i.e*. with homogeneous production choices, in order to investigate the importance of unobserved heterogeneity effects. The use of larger data sets poses additional challenges. Even farms mostly specialized in grain crops have different crop sets. *E.g*., some of them produce wheat, barley and rapeseed while others produce wheat, corn and surgarbeets. Specification and estimation of multicrop models with corner solutions remain open research questions in the agricultural production economic literature.

To consider crop aggregates is not satisfactory, especially when specific features of the agricultural production technology, *e.g*. crop rotation effects, are to be considered. Of course the difficulties due to the occurrence of corner solutions arise when considering single crops instead of crop aggregates as in our application. Our crop aggregates were mainly built for avoiding the occurrence of null acreages.

Our application only considers three crops or crop aggregates. In the random parameter multicrop model presented here the number of parameters to be estimated quadratically increases in the crop number, due to covariances of the random parameters. This calls for an for an adaptation of the “full random parameter” parameter approach adopted here.

Our considering a small time period and our focusing on short run choices lies at the root of our modeling the random parameter according to a unique, and stable across time, probability distribution. As discussed above, the main observed exogenous factors affecting agricultural production choices are the netput prices which mainly vary across time. This suggests that identification of the characteristics of the probability distribution of the random parameters with proper “exogenous variables variations” require observations covering long period. But Farmers’ technology choices and quasi-fixed factor endowments being impacted by netput prices, the probability distribution of the random parameters cannot be assumed to be constant along the considered period in this case.

Table 1. Selected parameter estimates, yield supply equations

	γ_k	$E[\beta_{k,i}]$	$Cov[\beta_{k,i}, \beta_{l,i}]$			$Var[v_{k,it}]$
			Wheat	**Cereals**	**Oilseeds**	
			($l = 1$)	($l = 2$)	($l = 0$)	
Wheat ($k = 1$)	0.710	7.952	0.992	0.807	0.555	0.595
	(0.116)	(0.092)	(0.119)	(0.121)	(0.072)	(0.038)
Cereals ($k = 2$)	0.140	7.167	0.807	1.215	0.509	1.077
	(0.098)	(0.103)	(0.121)	(0.173)	(0.081)	(0.040)
Oilseeds ($k = 0$)	0.174	5.265	0.555	0.509	0.428	0.852
	(0.105)	(0.061)	(0.072)	(0.081)	(0.057)	(0.035)

Note: standard errors are in parentheses

Table 2. Selected parameter estimates, acreage share equations

	Expectation	**Covariances with**				
		$\ln \alpha_i$	$\ln \rho_i$	$\ln \beta_{1,i}$	$\ln \beta_{2,i}$	$\ln \beta_{0,i}$
				Wheat	**Cereals**	**Oilseeds**
$\ln \alpha_i$	-2.357	0.196	0.112	0.008	0.019	0.010
	(0.042)	(0.027)	(0.02)	(0.005)	(0.007)	(0.005)
$\ln \rho_i$	-2.186	0.112	0.279	-0.012	0.007	-0.005
	(0.050)	(0.026)	(0.039)	(0.005)	(0.008)	(0.006)

Table 3. Fitting criteria of the model: pseudo R^2

	Pseudo R^2	
	Yields y_{kit}	"**Acreage shares** s_{kit}
Wheat ($k = 1$)	.73	.79
Cereals ($k = 2$)	.65	.84
Oilseeds ($k = 0$)	.51	.56

Table 4. Correlations between random parameters and farmers' characteristics

	$\beta_{1,i}$	$\beta_{2,i}$	$\beta_{0,i}$	α_i	ρ_i
	Wheat	**Other cereals**	**Oilseeds**		
Farm capital	0.172	0.126	0.262	0.165	0.003
	(0.079)	(0.200)	(0.007)	(0.092)	(0.973)
Root crop acreage	0.310	0.195	0.296	0.407	-0.027
	(0.001)	(0.059)	(0.002)	(0.001)	(0.781)
Farmer's age	0.308	0.206	0.282	0.157	-0.242
	(0.001)	(0.035)	(0.004)	(0.111)	(0.013)

Note: Student's Test p-values are in parentheses

Table 5. Characteristics of the distribution of acreage shares price elasticities

	Average	**Q5**	**Q25**	**Q50**	**Q75**	**Q95**
Wheat Acreage						
Wheat Price	0.43	0.24	0.32	0.39	0.49	0.77
Other cereals Price	-0.25	-0.61	-0.29	-0.18	-0.15	-0.11
Oilseeds Price	-0.14	-0.24	-0.16	-0.13	-0.11	-0.08
Other cereals acreage						
Wheat Price	-0.48	-1.19	-0.67	-0.36	-0.23	-0.14
Other cereals Price	0.61	0.22	0.33	0.49	0.79	1.33
Oilseeds Price	-0.14	-0.24	-0.16	-0.13	-0.11	-0.08
Oilseeds acreage						
Wheat Price	-0.37	-0.84	-0.45	-0.31	-0.20	-0.13
Other cereals Price	-0.23	-0.67	-0.29	-0.17	-0.10	-0.05
Oilseeds Price	0.50	0.17	0.31	0.43	0.65	0.95

Table 6. Simulated impacts on acreages of the price shock

	Random parameter model	Fixed parameter model	Fixed Individual effects model
Wheat Acreage			
Total change (ha)	-159 (-3.9%)	-44 (-0.9%)	-96 (-2.2%)
Average change (ha)	-2 (-4.5%)	-1 (-0.9%)	-1 (-2.3%)
Max change (ha)	<0.5 (<0.1%)	1 (+0.6%)	1 (+1%)
Min change (ha)	-7 (-17.0%)	-2 (-2.4%)	-5 (-9.3%)
Other cereals Acreage			
Total change (ha)	-183 (-5.6%)	-3 (-0.1%)	-178 (-4.7%)
Average change (ha)	-2 (-6.3%)	<0.5 (-0.1%)	-2 (-5.1%)
Max change (ha)	+2 (+11.7%)	1 (+1.8%)	<0.5 (<0.1%)
Min change (ha)	-8.8 (-20.0%)	-1 (-2.7%)	-8.8 (-20.0%)
Oilseeds acreage			
Total change (ha)	+342 (+12.1%)	+48 (+2.4%)	+274 (+12.8%)
Average change (ha)	+4 (+13.9%)	+1 (+2.4%)	+3 (+12.8%)
Max change (ha)	+13 (+38.2%)	+1 (+4.0%)	+9 (+21.8%)
Min change (ha)	1 (+3.1%)	<0.5 (+1.1%)	+1 (+4.5%)

Note: Numbers in parentheses correspond to percent changes compared to initial acreages

Figure 1. *Ex post* and *ex ante* probability distributions of the random parameters

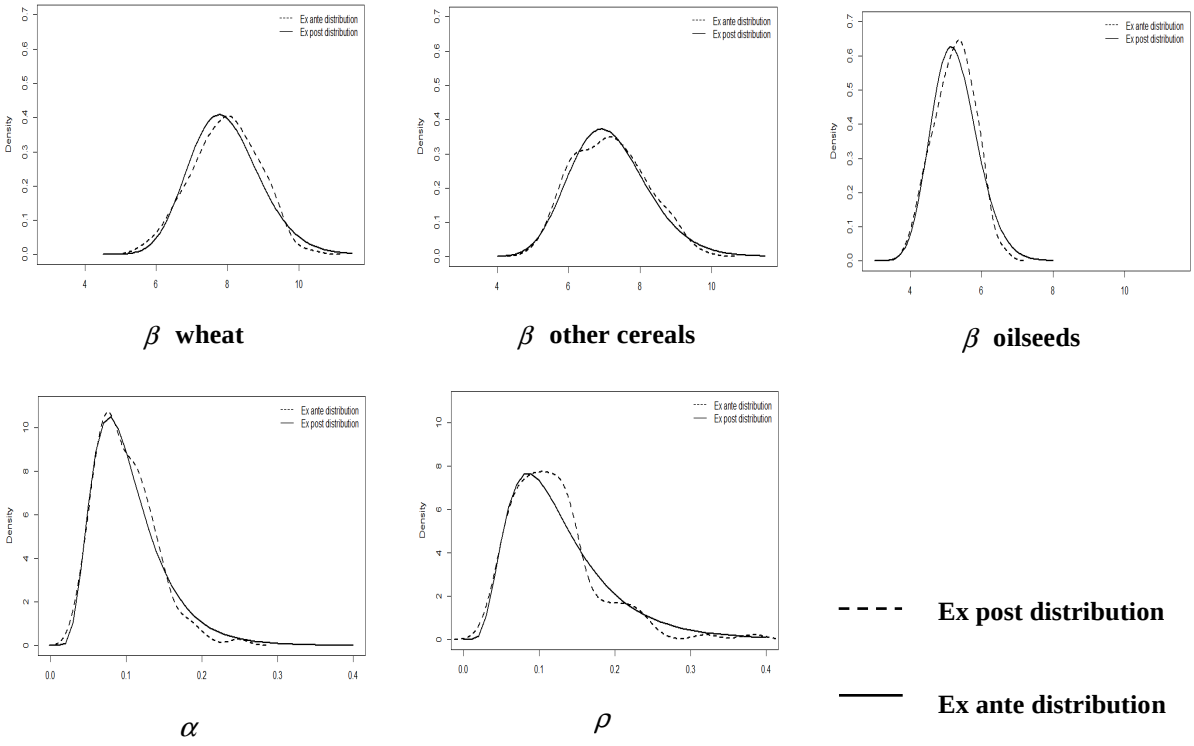
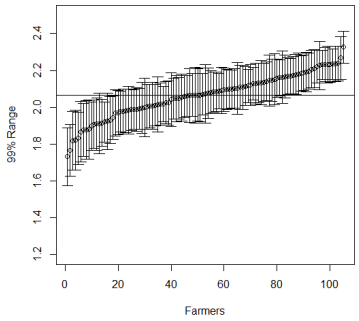
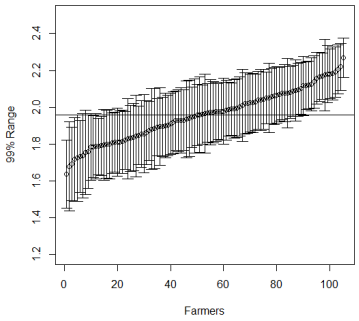


Figure 2. Calibrated values and confidence intervals of individual parameters

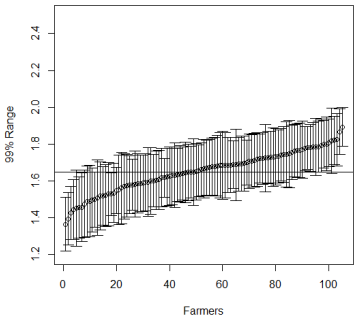
lnβ wheat



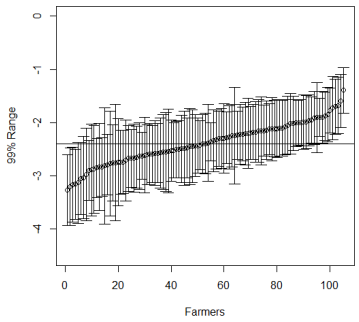
lnβ other cereals



lnβ oilseeds



lnα



lnρ

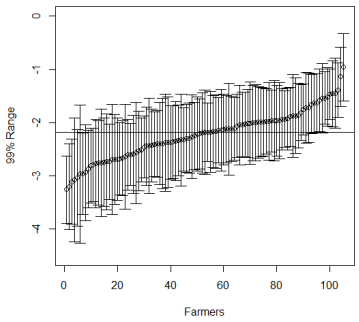


Figure 3. Distribution of selected random parameters across the population sample

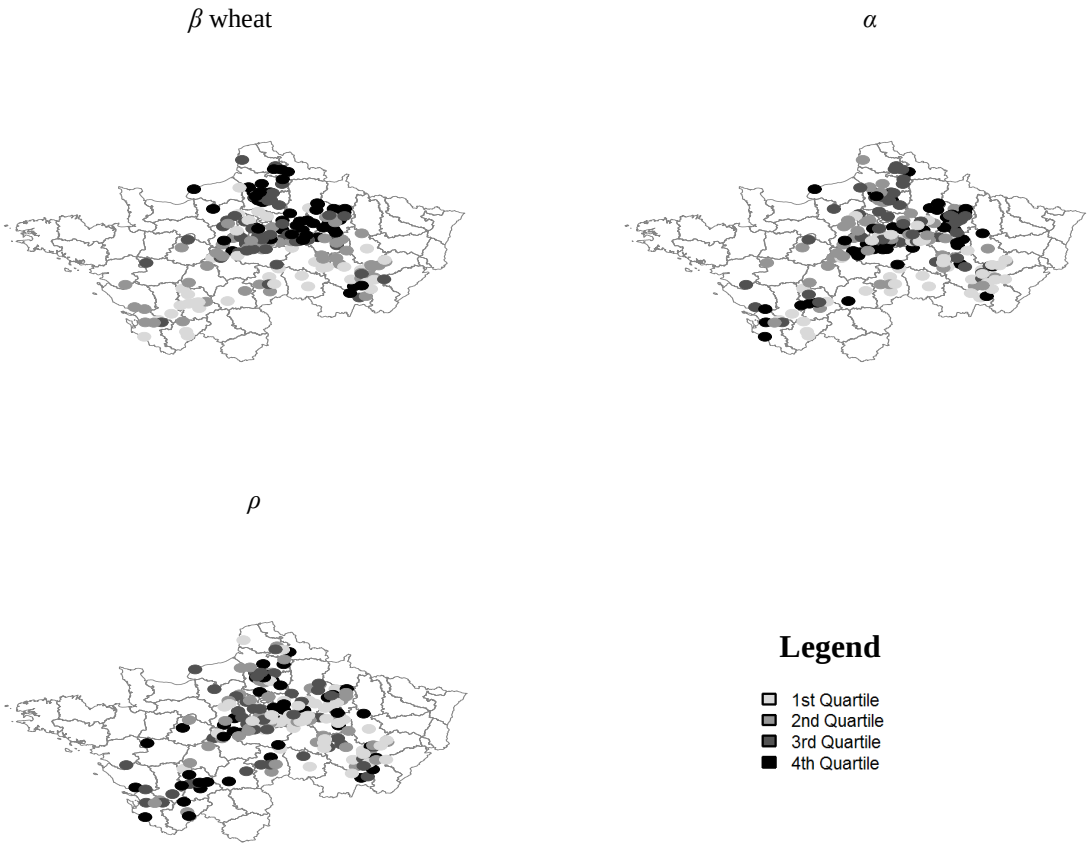
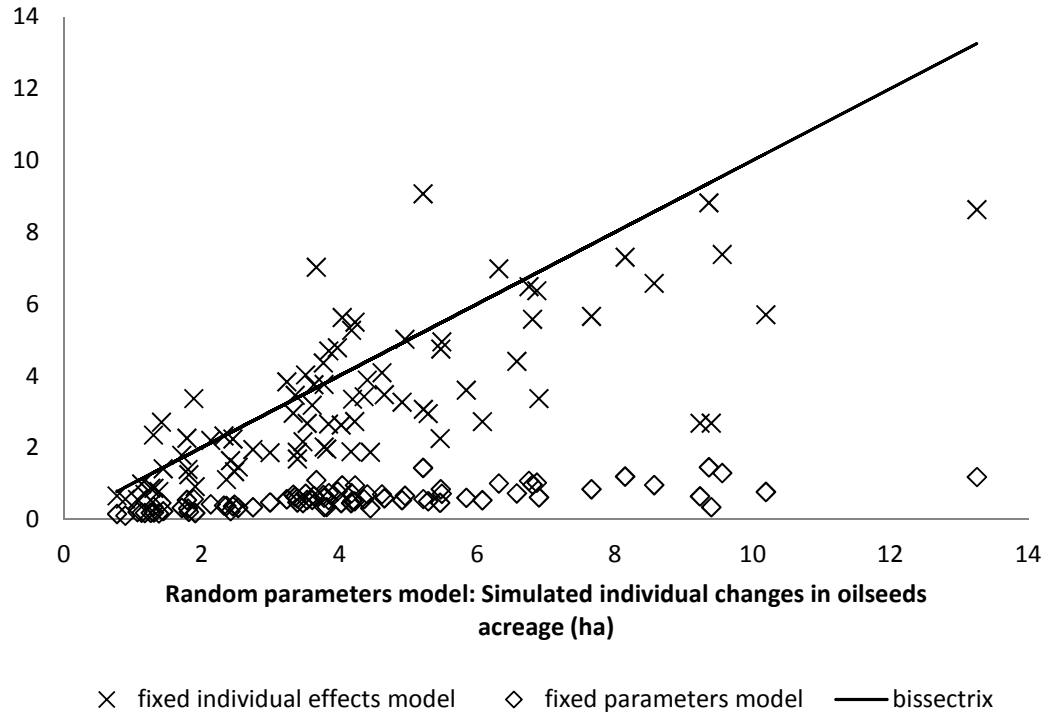


Figure 4. Impacts on oilseeds acreage simulated with the different models



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Technical Appendices

Appendix A. Yield supply and expected gross margin functions

The yield supply function of crop *k* given in equation (5a) is obtained by maximizing in the aggregate variable input level, $x_{k,it}$, the expected margin of crop *k*, $\pi_{k,it}$, under the assumptions that the yield function is quadratic in the aggregate variable input level:

(A.1) $y_{k,it} = \beta_{k,i} + \delta_{k,t} + v_{k,it} - 1/2 \times \gamma_k^{-1}(\lambda_{k,i} + \upsilon_{k,it} - x_{k,it})^2$ with $E[v_{k,it}] = E[\upsilon_{k,it}] = 0$

and that the random terms $\upsilon_{k,it}$ (which may include a year specific effect) are observed when the input level is decided.[20] This yield function is parameterized by two fixed parameters, the curvature parameter γ_k and the crop specific year effect $\delta_{k,t}$, and a random parameter $\beta_{k,i}$. It depends on the effects of random events represented by the centered error terms $v_{k,it}$ and $\upsilon_{k,it}$.

The optimal input level of farmer *i* in *t* on crop *k* is thus given by:

(A.2) $x_{k,it} = \lambda_{k,i} - \gamma_{k,0} w_{it} p_{k,it}^{-1} + \upsilon_{k,it}$

and the corresponding expected gross margin is given by:

(A.3) $\pi_{k,it} = p_{k,it}\beta_{k,i} + 1/2\gamma_{k,0} w_{it}^2 p_{k,it}^{-1} - w_{it}\lambda_{k,i}$.

This gross margin level is expected by the farmer at the time of his acreage choices, *i.e.* before the observation of the random events represented by $v_{k,it}$ and $\upsilon_{k,it}$, and of the year specific effect $\delta_{k,t}$. Input demand equation (A.2) is not included in the estimated multicrop

[20] Whether the random event effects $v_{k,it}$ and/or the year specific effects $\delta_{k,t}$ are observed or not doesn't matter. These effects are forgone by the considered (risk neutral) farmer.

models because the input use levels are not observed at the crop level in our data set. They are only recorded at the farm level, unfortunately.[21]

Due to insufficient variation of the aggregate input prices in our data set,[22] it is difficult to separately identify the probability distributions of the parameters $\lambda_{k,i}$ and $\chi_{k,i}$ empirically. This explains why the expected gross margin used in the acreage share model (5b) is not that given by equation (A.3). The term $\zeta_{k,i}$ in equation (5c) is given by $\zeta_{k,i} \simeq \chi_{k,i} - w_{it}\lambda_{k,i}$.

[21] This aggregation problem can be overcome by defining an input use allocation equation as in Carpentier and Letort (2012). However, this option would have increased significantly the complexity of the considered multicrop model and of its estimation.

[22] As well as due to our not modeling input demands.

Appendix B. Algorithms

This appendix presents the algorithm we used in three steps, after a brief presentation of the APIS simulator and of its interests and limits. First, we restate the basic SEM algorithm using the APIS simulator. Second, we show how the ideas underlying ECM proposed by Meng and Rubin (1993) can be used for designing a "SECM" algorithm simplifying the computations involved in the SEM algorithm. Finally we present the SAEM and its interests and show how the "SECM" algorithm can easily be adapted into a "SAECM" algorithm.

APIS simulator

The APIS simulator was employed by, *e.g.*, Caffo *et al* (2005) or Train (2007). It allows integrating by simulation method an expectation over the probability distribution of $\mathbf{q}_i$ conditional on $(\mathbf{c}_i, \mathbf{z}_i)$ by using draws for the marginal probability distribution of $\mathbf{q}_i$. It allows approximating

(B.1) $$E[\ln \kappa(\mathbf{c}_i, \mathbf{q}_i \mid \mathbf{z}_i; \boldsymbol{\theta}) \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}_{n-1}] \equiv \int \ln \kappa(\mathbf{c}_i, \mathbf{q} \mid \mathbf{z}_i; \boldsymbol{\theta}) h(\mathbf{q} \mid \mathbf{z}_i, \mathbf{c}_i; \boldsymbol{\theta}_{n-1}) d\mathbf{q}$$

by

(B.2) $$S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \sum_{t=1}^{T} \ln \kappa(\mathbf{c}_{it}, \tilde{\mathbf{q}}_{i,s,n-1} \mid \mathbf{z}_{it}; \boldsymbol{\theta})$$

where the

(B.3) $$\tilde{\mathbf{q}}_{i,s,n-1} \equiv \tilde{\mathbf{q}}_{i,s}(\boldsymbol{\eta}_{n-1})$$

terms are independent random draws from $h(\mathbf{q}; \boldsymbol{\eta}_{n-1})$ for $s = 1, ..., S_n$ and $i = 1, ..., N$, and

(B.4) $$\tilde{\omega}_{i,s,n-1} \equiv \tilde{\omega}_{i,s}(\boldsymbol{\theta}_{n-1}) \equiv \frac{f(\mathbf{c}_i \mid \mathbf{z}_i, \tilde{\mathbf{q}}_{i,s,n-1}; \boldsymbol{\mu}_{n-1})}{S_n^{-1} \sum_{s=1}^{S_n} f(\mathbf{c}_i \mid \mathbf{z}_i, \tilde{\mathbf{q}}_{i,s,n-1}; \boldsymbol{\mu}_{n-1})}$$

for $s = 1, ..., S_n$ and $i = 1, ..., N$.

The APIS simulator can be interpreted as an importance sampling simulator with $h(\mathbf{q}_i;\boldsymbol{\eta})$ as the proposal probability density function. This proposal probability density function is inefficient because $h(\mathbf{q}_i;\boldsymbol{\eta})$ is unlikely to be close to $h(\mathbf{q}_i \mid \mathbf{z}_i,\mathbf{c}_i;\boldsymbol{\theta})$ in cases where $\mathbf{c}_i$ explicitly is a function of $\mathbf{q}_i$ and where $\mathbf{q}_i$ exhibits significant variability. But the simplicity of this simulator allows using very large random draw numbers for approximating $f(\mathbf{c}_i \mid \mathbf{z}_i;\boldsymbol{\theta})$. This estimator also is fairly easy to code.

Expectations such as $E[\ln \kappa(\mathbf{c}_i,\mathbf{q}_i \mid \mathbf{z}_i;\boldsymbol{\theta}) \mid \mathbf{z}_i,\mathbf{c}_i;\boldsymbol{\theta}_{n-1}]$ can be integrated by using draws from $h(\mathbf{q}_i \mid \mathbf{z}_i,\mathbf{c}_i;\boldsymbol{\theta})$. But such draws are more difficult to obtain. *E.g.*, it is always possible to obtain Metropolis-Hastings (quasi-)random draws from $h(\mathbf{q}_i \mid \mathbf{z}_i,\mathbf{c}_i;\boldsymbol{\theta})$. But this simulation technique consists in a rather long process to be repeated at each iteration of the SEM algorithm. The APIS simulator appears to be more convenient because (quasi-)random draws from $h(\mathbf{q}_i;\boldsymbol{\eta})$ are easily obtained.

The algorithms to be defined rely on the simulated versions of the conditional expectation of the sample log-likelihood function $N^{-1}\sum_{i=1}^{N} E[\ln \kappa(\mathbf{c}_i,\mathbf{q}_i \mid \mathbf{z}_i;\boldsymbol{\theta}) \mid \mathbf{z}_i,\mathbf{c}_i;\boldsymbol{\theta}_{n-1}]$ of the complete data vector:

$$\text{(B.5)}\quad \tilde{Q}_{N,n}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1}) \equiv N^{-1}\sum_{i=1}^{N} S_n^{-1}\sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1}\sum_{t=1}^{T} \ln \kappa(\mathbf{c}_{it},\tilde{\mathbf{q}}_{i,s,n-1} \mid \mathbf{z}_{it};\boldsymbol{\theta})$$

and, using $\ln \kappa(\mathbf{c}_{it},\mathbf{q} \mid \mathbf{z}_{it};\boldsymbol{\theta}) = \ln f(\mathbf{c}_{it} \mid \mathbf{z}_{it},\mathbf{q};\boldsymbol{\mu}) + \ln h(\mathbf{q};\boldsymbol{\eta})$, its decomposition given by

$$\text{(B.6)}\quad \tilde{Q}_{N,n}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1}) = \tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu} \mid \boldsymbol{\theta}_{n-1}) + \tilde{Q}^{\mathbf{q}}_{N,n}(\boldsymbol{\eta} \mid \boldsymbol{\theta}_{n-1})$$

with

$$\text{(B.7)}\quad \tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu} \mid \boldsymbol{\theta}_{n-1}) \equiv N^{-1}\sum_{i=1}^{N} S_n^{-1}\sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1}\sum_{t=1}^{T} \ln f(\mathbf{c}_{it} \mid \mathbf{z}_{it},\tilde{\mathbf{q}}_{i,s,n-1};\boldsymbol{\mu})$$

and:

$$\text{(B.8)}\quad \tilde{Q}^{\mathbf{q}}_{N,n}(\boldsymbol{\eta} \mid \boldsymbol{\theta}_{n-1}) \equiv N^{-1}\sum_{i=1}^{N} S_n^{-1}\sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \ln h(\tilde{\mathbf{q}}_{i,s,n-1};\boldsymbol{\eta}).$$

SEM algorithm

The APIS Simulator allows designing a simple SEM algorithm. The "recursive estimator" proposed by Train (2007, 2008, 2009), as well as its extensions, are computed by using such SEM algorithms. The SEM algorithm iterates a sequence composed of a SE step and of a M step.

SE step. Integration of the conditional expectations

Obtain independent (quasi-)random draws[23] $\tilde{\mathbf{q}}_{i,s,n-1}$ from $h(\mathbf{q};\boldsymbol{\eta}_{n-1})$ and compute the weight terms $\tilde{\omega}_{i,s,n-1}$ for $s=1,...,S_n$ and $i=1,...,N$.

M step. Update of the value of $\boldsymbol{\theta} \equiv (\boldsymbol{\mu},\boldsymbol{\eta})$

Compute:

(B.9) $\boldsymbol{\theta}_n \equiv \arg\max_{\boldsymbol{\theta}} \tilde{Q}_{N,n}(\boldsymbol{\theta}\,|\,\boldsymbol{\theta}_{n-1})$

or, equivalently:

(B.10a) $\boldsymbol{\mu}_n \equiv \arg\max_{\boldsymbol{\mu}} \tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu}\,|\,\boldsymbol{\theta}_{n-1})$

and

(B.10b) $\boldsymbol{\eta}_n \equiv \arg\max_{\boldsymbol{\eta}} \tilde{Q}^{\mathbf{q}}_{N,n}(\boldsymbol{\eta}\,|\,\boldsymbol{\theta}_{n-1})$.

The decomposition of the maximization problem of $\tilde{Q}_{N,n}(\boldsymbol{\theta}\,|\,\boldsymbol{\theta}_{n-1})$ in $\boldsymbol{\theta}$ into the maximization problems of $\tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu}\,|\,\boldsymbol{\theta}_{n-1})$ in $\boldsymbol{\mu}$ and of $\tilde{Q}^{\mathbf{q}}_{N,n}(\boldsymbol{\eta}\,|\,\boldsymbol{\theta}_{n-1})$ in $\boldsymbol{\eta}$ illustrates the main interest in using EM algorithms for estimating random parameter models. This decomposition is specific to models involving latent/hidden variables such as random parameter models.

[23] Pseudo-random sequence

"SCME" algorithm

With $\ln h(\mathbf{q};\boldsymbol{\eta}) = \ln h(\mathbf{q};\mathbf{a},\boldsymbol{\Omega})$ we observe that $\tilde{Q}^{\mathbf{q}}_{N,n}(\boldsymbol{\eta} \mid \boldsymbol{\theta}_{n-1}) = \tilde{Q}^{\mathbf{q}}_{N,n}(\mathbf{a},\boldsymbol{\Omega} \mid \boldsymbol{\theta}_{n-1})$ is easily maximized in $(\mathbf{a},\boldsymbol{\Omega})$. It is the weighted log-likelihood function of a multivariate normal variable. Further decomposing $\ln f(\mathbf{c}_{it} \mid \mathbf{z}_{it},\mathbf{q};\boldsymbol{\mu})$, and thus $\tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu} \mid \boldsymbol{\theta}_{n-1})$, suggest further simplification for the M step. With

(B.11) $\ln f(\mathbf{c}_{it} \mid \mathbf{z}_{it},\mathbf{q};\boldsymbol{\mu}) = \ln f(\mathbf{y}_{it} \mid \mathbf{z}_{it},\mathbf{q};\boldsymbol{\gamma},\boldsymbol{\delta},\boldsymbol{\Lambda}) + \ln f(\mathbf{s}_{it} \mid \mathbf{z}_{it},\mathbf{q};\boldsymbol{\gamma},\boldsymbol{\Psi})$

the terms

(B.12) $\tilde{Q}^{\mathbf{y}}_{N,n}(\boldsymbol{\gamma},\boldsymbol{\delta},\boldsymbol{\Lambda} \mid \boldsymbol{\theta}_{n-1}) \equiv N^{-1}\sum_{i=1}^{N} S_n^{-1}\sum_{s=1}^{S_n}\tilde{\omega}_{i,s,n-1}\sum_{t=1}^{T}\ln f(\mathbf{y}_{it} \mid \mathbf{z}_{it},\tilde{\mathbf{q}}_{i,s,n-1};\boldsymbol{\gamma},\boldsymbol{\delta},\boldsymbol{\Lambda})$,

corresponding to the yield supply function sub-system, and

(B.13) $\tilde{Q}^{\mathbf{s}}_{N,n}(\boldsymbol{\gamma},\boldsymbol{\Psi} \mid \boldsymbol{\theta}_{n-1}) \equiv N^{-1}\sum_{i=1}^{N} S_n^{-1}\sum_{s=1}^{S_n}\tilde{\omega}_{i,s,n-1}\sum_{t=1}^{T}\ln f(\mathbf{s}_{it} \mid \mathbf{z}_{it},\tilde{\mathbf{q}}_{i,s,n-1};\boldsymbol{\gamma},\boldsymbol{\Psi})$,

corresponding to the acreage choice sub-system, are weighted log-likelihood function of multivariate Gaussian linear (in $\boldsymbol{\delta}$ and $\boldsymbol{\gamma}$) regression models. Since these terms both depend on $\boldsymbol{\gamma}$, the maximization of

(B.14) $\tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu} \mid \boldsymbol{\theta}_{n-1}) = \tilde{Q}^{\mathbf{y}}_{N,n}(\boldsymbol{\delta},\boldsymbol{\gamma},\boldsymbol{\Lambda} \mid \boldsymbol{\theta}_{n-1}) + \tilde{Q}^{\mathbf{s}}_{N,n}(\boldsymbol{\gamma},\boldsymbol{\Psi} \mid \boldsymbol{\theta}_{n-1})$

in $\boldsymbol{\mu} \equiv (\boldsymbol{\delta},\boldsymbol{\gamma},\boldsymbol{\Lambda},\boldsymbol{\Psi})$ cannot be split into two simpler maximization problems corresponding to the yield supply function and acreage choices sub-system. Even though, to maximize $\tilde{Q}^{\mathbf{y}}_{N,n}(\boldsymbol{\delta},\boldsymbol{\gamma},\boldsymbol{\Lambda} \mid \boldsymbol{\theta}_{n-1})$ in $(\boldsymbol{\delta},\boldsymbol{\gamma},\boldsymbol{\Lambda})$ or to maximize $\tilde{Q}^{\mathbf{s}}_{N,n}(\boldsymbol{\gamma},\boldsymbol{\Psi} \mid \boldsymbol{\theta}_{n-1})$ in $(\boldsymbol{\gamma},\boldsymbol{\Psi})$ requires the use of nonlinear optimization algorithms. Of course a simple Gauss-Seidel algorithm, the so-called Iterative Feasible Generalized Least Squares, can be used here.

The ECM algorithms proposed by Meng and Rubin (1993) allow simplifying M steps. It is possible to replace a M step, *e.g.* the direct maximization $\tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu} \mid \boldsymbol{\theta}_{n-1})$ in $\boldsymbol{\mu}$, by a sequence of simpler maximization problems, *i.e.* a sequence of Conditional M (CM) steps. This

sequence of CM steps sequentially updates the value of $\boldsymbol{\mu}$ according to a predetermined partition of this parameter vector. The objective of these CM steps is to update the value of $\boldsymbol{\mu}$, not by maximizing $\tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu}\,|\,\boldsymbol{\theta}_{n-1})$ in $\boldsymbol{\mu}$, but by simply computing a value of $\boldsymbol{\mu}$ such that $\tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu}\,|\,\boldsymbol{\theta}_{n-1}) > \tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\mu}_{n-1}\,|\,\boldsymbol{\theta}_{n-1})$, if possible.[24] We used the following SECM algorithm because it only involves very simple CM steps:

SE step. Integration of the conditional expectations

Obtain independent random draws $\tilde{\mathbf{q}}_{i,s,n-1}$ from $h(\mathbf{q};\boldsymbol{\eta}_{n-1})$ and compute the weight terms $\tilde{\omega}_{i,s,n-1}$ for $s=1,...,S_n$ and $i=1,...,N$.

CM step. Conditional update of the value of $\boldsymbol{\theta} \equiv (\boldsymbol{\mu},\boldsymbol{\eta})$

Compute:

(B.15a) $\mathbf{a}_n \equiv \arg\max_{\mathbf{a}} \tilde{Q}^{\mathbf{q}}_{N,n}(\mathbf{a},\boldsymbol{\Omega}_{n-1}\,|\,\boldsymbol{\theta}_{n-1})$,

(B.15b) $\boldsymbol{\Omega}_n \equiv \arg\max_{\boldsymbol{\Omega}} \tilde{Q}^{\mathbf{q}}_{N,n}(\mathbf{a}_n,\boldsymbol{\Omega}\,|\,\boldsymbol{\theta}_{n-1})$,

(B.15c) $\boldsymbol{\Psi}_n \equiv \arg\max_{\boldsymbol{\Psi}} \tilde{Q}^{\mathbf{s}}_{N,n}(\boldsymbol{\gamma}_{n-1},\boldsymbol{\Psi}\,|\,\boldsymbol{\theta}_{n-1}) = \arg\max_{\boldsymbol{\Psi}} \tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\gamma}_{n-1},\boldsymbol{\delta}_{n-1},\boldsymbol{\Lambda}_{n-1},\boldsymbol{\Psi}\,|\,\boldsymbol{\theta}_{n-1})$,

(B.15d) $\boldsymbol{\Lambda}_n \equiv \arg\max_{\boldsymbol{\Lambda}} \tilde{Q}^{\mathbf{y}}_{N,n}(\boldsymbol{\gamma}_{n-1},\boldsymbol{\delta}_{n-1},\boldsymbol{\Lambda}\,|\,\boldsymbol{\theta}_{n-1}) = \arg\max_{\boldsymbol{\Lambda}} \tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\gamma}_{n-1},\boldsymbol{\delta}_{n-1},\boldsymbol{\Lambda},\boldsymbol{\Psi}_n\,|\,\boldsymbol{\theta}_{n-1})$

and:

(B.15e) $$(\boldsymbol{\gamma}_n,\boldsymbol{\delta}_n) \equiv \begin{cases} (\boldsymbol{\gamma}_*,\boldsymbol{\delta}_*) \text{ if } \tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\gamma}_*,\boldsymbol{\delta}_*,\boldsymbol{\Lambda}_n,\boldsymbol{\Psi}_n\,|\,\boldsymbol{\theta}_{n-1}) > \tilde{Q}^{\mathbf{c}}_{N,n}(\boldsymbol{\gamma}_{n-1},\boldsymbol{\delta}_{n-1},\boldsymbol{\Lambda}_n,\boldsymbol{\Psi}_n\,|\,\boldsymbol{\theta}_{n-1}) \\ (\boldsymbol{\gamma}_{n-1},\boldsymbol{\delta}_{n-1}) \text{ otherwise} \end{cases}$$

where:

[24] In their seminal article, Dempster *et al* (1997) also considered this extension of the standard M step to define an extension of the standard EM algorithm which they designated as the Generalized EM (GEM) algorithm.

(B.15e) $(\boldsymbol{\gamma}_*, \boldsymbol{\delta}_*) \equiv \arg\max_{(\boldsymbol{\gamma},\boldsymbol{\delta})} \tilde{Q}^{\mathrm{y}}_{N,n}(\boldsymbol{\gamma}, \boldsymbol{\delta}, \boldsymbol{\Lambda}_n \mid \boldsymbol{\theta}_{n-1})$.[25]

In our case, the terms $\mathbf{a}_n$, $\boldsymbol{\Omega}_n$, $\boldsymbol{\Psi}_n$, $\boldsymbol{\Lambda}_n$ and $(\boldsymbol{\gamma}_n, \boldsymbol{\delta}_n)$ have analytical closed form solutions:

(B.16a) $\mathbf{a}_n = N^{-1} \sum_{i=1}^{N} S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \tilde{\mathbf{q}}_{i,s,n-1}$

(B.16b) $\boldsymbol{\Omega}_n = N^{-1} \sum_{i=1}^{N} S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \tilde{\mathbf{q}}_{i,s,n-1} \tilde{\mathbf{q}}'_{i,s,n-1} - \mathbf{a}_n \mathbf{a}'_n$

(B.16c) $\boldsymbol{\Psi}_n = N^{-1} \sum_{i=1}^{N} S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \sum_{t=1}^{T} \mathbf{u}_{it}(\tilde{\mathbf{q}}_{i,s,n-1}; \boldsymbol{\gamma}_{n-1}) \mathbf{u}_{it}(\tilde{\mathbf{q}}_{i,s,n-1}; \boldsymbol{\gamma}_{n-1})'$

(B.16d) $\boldsymbol{\Lambda}_n = N^{-1} \sum_{i=1}^{N} S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \sum_{t=1}^{T} \mathbf{v}_{it}(\tilde{\mathbf{q}}_{i,s,n-1}; \boldsymbol{\gamma}_{n-1}, \boldsymbol{\delta}_{n-1}) \mathbf{v}_{it}(\tilde{\mathbf{q}}_{i,s,n-1}; \boldsymbol{\gamma}_{n-1}, \boldsymbol{\delta}_{n-1})'$

and:

(B.16e) $(\boldsymbol{\gamma}_n, \boldsymbol{\delta}_n) \equiv \left(\sum_{i=1}^{N} \sum_{t=1}^{T} \mathbf{Z}_{it} \boldsymbol{\Lambda}_n^{-1} \mathbf{Z}'_{it} \right)^{-1} \sum_{i=1}^{N} S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \sum_{t=1}^{T} \mathbf{Z}_{it} \boldsymbol{\Lambda}_n^{-1} (\mathbf{y}_{it} - \tilde{\boldsymbol{\beta}}_{i,s,n-1})$

with obvious notations.

"SACME" algorithm

When new random terms $\tilde{\mathbf{q}}_{i,s,n-1}$ are drawn at each iteration, the numerical convergence of SECM algorithm may be difficult due to the simulation noise. Delyon *et al* (1999) proposed the SAEM algorithms in order to attenuate this problem. In the SAEM algorithms the M step

[25] The update of $(\boldsymbol{\gamma}, \boldsymbol{\delta})$ given in equations (B.15e) and (B.15f) is used to overcome the maximization of $\tilde{Q}^{\mathrm{c}}_{N,n}(\boldsymbol{\gamma}, \boldsymbol{\delta}, \boldsymbol{\Lambda}_n, \boldsymbol{\Psi}_n \mid \boldsymbol{\theta}_{n-1})$ in $(\boldsymbol{\gamma}, \boldsymbol{\delta})$. The solution in $(\boldsymbol{\gamma}, \boldsymbol{\delta})$ to this maximization problem has an analytical closed form solution in the case considered here, *i.e.* for the "random parameter" model. But the counterparts of this maximization problem for the "fixed parameters" and the "individual effects" models need to be numerically solved in $(\boldsymbol{\gamma}, \boldsymbol{\delta})$ and in $(\alpha, \boldsymbol{\rho})$. The parameters $\boldsymbol{\gamma}$ and $\boldsymbol{\delta}$ are identified by the yield supply function sub-system. The parameter $\boldsymbol{\gamma}$ enters the acreage choice model because expected yields partly determine these choices. For the "random parameter" model the update of $(\boldsymbol{\gamma}, \boldsymbol{\delta})$ could have been defined as:

$(\boldsymbol{\gamma}_n, \boldsymbol{\delta}_n) \equiv \mathrm{argmax}_{(\boldsymbol{\gamma},\boldsymbol{\delta})} \tilde{Q}^{\mathrm{c}}_{N,n}(\boldsymbol{\gamma}, \boldsymbol{\delta}, \boldsymbol{\Lambda}_n, \boldsymbol{\Psi}_n \mid \boldsymbol{\theta}_{n-1})$.

(or the sequence of CM steps) is modified in order to "smooth" out the objective functions considered along the SE(C)M iteration process. *E.g.*, the objective function of the M step of the SEM algorithm given above, *i.e.* $\tilde{Q}_{N,n}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1})$, is replaced by:

(B.17a) $\tilde{P}_{N,n}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1}) \equiv (1-\vartheta_n) \times \tilde{P}_{N,n-1}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-2}) + \vartheta_n \times \tilde{Q}_{N,n}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1})$

or, equivalently, by

(B.17b) $\tilde{P}_{N,n}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_1) = \sum_{j=1}^{n-1}\left(\prod_{m=j+1}^{n}(1-\vartheta_m)\right) \times \vartheta_j \times \tilde{Q}_{N,j}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{j-1}) + \vartheta_n \times \tilde{Q}_{N,n}(\boldsymbol{\theta} \mid \boldsymbol{\theta}_{n-1})$

where ϑ_n is a decreasing sequence of positive step size such that:

(B.18) $\vartheta_1 = 1,\ \sum_{n=1}^{+\infty} \vartheta_n = +\infty$ and $\sum_{n=1}^{+\infty} (\vartheta_n)^2 < +\infty$.

The "SACME" algorithm we used for computing the estimators of our random parameter multicrop model is defined by:

SE step. Integration of the conditional expectations

Obtain independent random draws $\tilde{\mathbf{q}}_{i,s,n-1}$ from $h(\mathbf{q}; \boldsymbol{\eta}_{n-1})$ and compute the weight terms $\tilde{\omega}_{i,s,n-1}$ for $s = 1,...,S_n$ and $i = 1,...,N$.

CM step. Conditional update of the value of $\boldsymbol{\theta} \equiv (\boldsymbol{\mu}, \boldsymbol{\eta})$

Compute:

(B.19a)
$$\mathbf{a}_n = (1-\vartheta_n) \times \mathbf{a}_{n-1} + \vartheta_n \times N^{-1} \sum_{i=1}^{N} S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \tilde{\mathbf{q}}_{i,s,n-1}$$

(B.19b)
$$\boldsymbol{\Omega}_n = (1-\vartheta_n) \times (\boldsymbol{\Omega}_{n-1} + \mathbf{a}_n \mathbf{a}_n') + \vartheta_n \times N^{-1} \sum_{i=1}^{N} S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \tilde{\mathbf{q}}_{i,s,n-1} \tilde{\mathbf{q}}_{i,s,n-1}' - \mathbf{a}_n \mathbf{a}_n'$$

(B.19c)
$$\boldsymbol{\Psi}_n = (1-\vartheta_n) \times \boldsymbol{\Psi}_{n-1} + \vartheta_n \times N^{-1} \sum_{i=1}^{N} S_n^{-1} \sum_{s=1}^{S_n} \tilde{\omega}_{i,s,n-1} \sum_{t=1}^{T} \mathbf{u}_{it}(\tilde{\mathbf{q}}_{i,s,n-1}; \boldsymbol{\gamma}_{n-1}) \mathbf{u}_{it}(\tilde{\mathbf{q}}_{i,s,n-1}; \boldsymbol{\gamma}_{n-1})'$$

(B.19d)

$$\boldsymbol{\Lambda}_n = (1-\vartheta_n)\times\boldsymbol{\Lambda}_{n-1} + \vartheta_n \times N^{-1}\sum_{i=1}^{N} S_n^{-1}\sum_{s=1}^{S_n}\tilde{\omega}_{i,s,n-1}\sum_{t=1}^{T}\mathbf{v}_{it}(\tilde{\mathbf{q}}_{i,s,n-1};\boldsymbol{\gamma}_{n-1},\boldsymbol{\delta}_{n-1})\mathbf{v}_{it}(\tilde{\mathbf{q}}_{i,s,n-1};\boldsymbol{\gamma}_{n-1},\boldsymbol{\delta}_{n-1})'$$

and:

(B.19e)

$$(\boldsymbol{\gamma}_n,\boldsymbol{\delta}_n) = \left(\sum_{i=1}^{N}\sum_{t=1}^{T}\mathbf{Z}_{it}\boldsymbol{\Lambda}_n^{-1}\mathbf{Z}_{it}'\right)^{-1}\sum_{j=1}^{n}\phi_{j,n}\sum_{i=1}^{N}S_j^{-1}\sum_{s=1}^{S_j}\tilde{\omega}_{i,s,j-1}\sum_{t=1}^{T}\mathbf{Z}_{it}\boldsymbol{\Lambda}_n^{-1}(\mathbf{y}_{it}-\tilde{\boldsymbol{\beta}}_{i,s,j-1})$$

where

(B.20) $\phi_{j,n} \equiv \left(\prod_{m=j+1}^{n}(1-\vartheta_m)\right)\times\vartheta_j$ for $j = 1,...,n-1$ and $\phi_{n,n} \equiv \vartheta_n$.

Monitoring and stopping rule of the algorithm

The calibration of the sequence steps ϑ_n and a suitable stopping rule for the "SACME" algorithm are essential criteria for its convergence. SAEM algorithms are shown to theoretically converge if ϑ_n is a positive sequence steps satisfying conditions (B.18). We used a standard decreasing sequence of positive step sizes (see, *e.g.*, Jank 2006 ; Polyak and Juditski 1992) :

(B.21) $\vartheta_1 = 1,\ \vartheta_n = n^{-\nu}$ with $\nu \in (1/2,1]$.

We retained $\nu = 0.7$ after several trials.

We also used a standard stopping rule (Booth and Hobert 1999 ; Booth *et al* 2001) based on the relative changes in the values of the estimated parameters from an iteration to the next one. The algorithm stops when the following condition:

(B.22) $$\max_j\left(\frac{\left|\theta_{j,n}-\theta_{j,n-1}\right|}{\left|\theta_{j,n}\right|+\sigma_1}\right) < \sigma_2$$

holds for three consecutive iterations for chosen positive values of the convergence parameters σ_1 and σ_2. Several iterations need to be considered due to the simulation noise generated by the random draws of the $\mathbf{q}_i$ terms at each iteration (see, *e.g.*, Booth and Hobert

1999). We set up $\sigma_1 = 0.01$ and $\sigma_2 = 0.001$. Because condition (B.22) may hold for $\boldsymbol{\theta}_{n-2}$, $\boldsymbol{\theta}_{n-1}$ and $\boldsymbol{\theta}_n$ even if these parameter values do not (approximately) achieve the maximum of the considered likelihood function, we checked that the scores were null and that the Hessian matrix was negative definite at the estimated value of $\boldsymbol{\theta}$ (Gu and Zhu 2001).